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Introduction

The double geodetic Corsica site (Aspretto-Senetosa, Plate 1) is dedicated to the absolute calibration experiment in the framework of the Jason-1 mission. While Aspretto (near Ajaccio) will be used to concentrate satellite tracking techniques (SLR, DORIS, GPS) to locally improve orbits, Senetosa permits the realization of the closure equation (tige gauges / altimeter). The particular contribution of Senetosa is to determine altimeter bias with 10 Hz altimetric data (GDR-Ms) from 20 km off-shore to the coast using only coastal tide gauges. For doing this, a local marine geoid has been determined using kinematic GPS (see "Leveling the Sea Surface using a GPS Catamaran" poster). Three permanent tide gauges (AANDERAA, Plate 1 and Photo 1) have been installed since may 1998 with a 5 min data sampling rate. In 2000, two of them have been displaced in a more protected area (M4/M5) and placed close together to better monitor tide gauges behavior. This redundancy allows the continuous determination of altimeter bias by limiting the impact of tide gauges period of outages or erroneous data. At the begining of this year a meteorological station has been installed near the light house.

The slight degradation of Side A and finally the use of Side B of ALT altimeter (since cycle 236) gives us the opportunity to check the Corsica site in the frame of linking altimetric missions. We first present the "1- Calibration Process" (method and corrections) and the "2- Impact of Environment Parameters" such as SWH and geoid slope. "4- Calibration Results" are then discussed. Finally, "4- Capraia side project" is presented.



Figure 1a illustrates the calibration process. In a first step, 10 Hz altimetric sea heights (upper panel) are corrected from geoid slope by computing the sea height differences from the altimetric data location to each tide gauge location (Figure 1a, 3 lower panels). At each altimetric data location, the mean geoid height is computed inside the footprint area (Figure 1a, left panel) which size is defined by the formula given in Chelton et al. (1989). At the tide gauges locations the geoid heights are constant and have been determined by the mean of GPS sea heights of the 99 Catamaran campaign. In a second step, tide gauges data are linearly interpolated for each 10 Hz altimetric data time (Figure 1a, 3 lower panels). The mean values of sea height differences, and the associated standard deviations, are then computed (Haltimeter - Htide gauges) for each tide gauge. This gives the estimated impact of altimeter range bias on the sea height determination. Altimeter bias is thus defined in the following as the difference between altimetric determination and "in-situ sea height". The corrections used for altimetric sea heights determination are listed at the bottom of Figure 1a and an example of their time evolution on the overflight time scale (few seconds) is given in Figure 1b. They follow the recommandations of the AVISO handbook [AVISO, 1996] allowing users to use our bias determination in agreement with their sea level letermination. NASA orbits have been used for this study.





Contour map represents the geoid heights determined from Catamaran GPS measurements.

Photo 1. Tide gauge leveling at M3 location.

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Figure 3. T/P Sea heights (1/10s) corrected from geoid slopes at tide gauge (M2) location. Red lines correspond to filtered heights using low-pass filter with 2 km cutof Upper panel is a zoom for filtered heights.

In this part we want to study the possible correlation with some parameters linked to the calibration process. Figures 2a and 2b give respectively the calibration value (bias) and its standard deviation as a function of (from top to bottom):

- Point of Closest Approach (PCA) distance (across-track, negative for west) - Point of Closest Measurement (PCM) distance
- Wind Speed
- Significant Wave Height (SWH) - Standard deviation of tide gauge measurements
- Number of 10 Hz altimetric data used - Standard deviation of 10 Hz altimetric data.

No clear correlation have been evidenced except for very low wind speed (and then SWH, cycle 241). Tide gauges data dispersion and across track distance seems to have very low impacts. The standard deviation of bias determination seems to be mainly due to 10 Hz altimetric data precision (at least half part). On the other hand, the geoid gradient determined during the 99 GPS Catamaran campaign seems to well represent what T/P altimeter "sees". Figure 3 shows the corrected sea surface heights profiles at M2 location as a function of along-track PCA distance. The observed signal which represents differences between geoid grid and mean T/P sea heights (over 1 year) have a standard deviation of 1 cm. The main part of the signal seems to be linked to coast vicinity, probably due to corrupted altimetric signal. This leads us to limit the altimeter data processing to those at more than 5 km along-track distance from PCA (see Figure 1a).



2- Impact of Environmental Parameters



		T/P Calibratic
		Standard deviation
Standard Deviation of mean calibration (mm)	150 100 50 -100	-50 -50
	150 100 50 0 0	
	150 100 50 0 -0.5	
	150 100 50 0 0	
	150 100 50 0 0	
	150 100 50 0 0	0.05 S
	150 100 50 0 15	⊖
	150 100 50 0	

Figure 2. Calibration results as a function of parameters. (a, left) for Calibration (bias). (b, right) for Standard deviation of bias determination.

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€0-000 Bab 000) -
Mean calibration (mm)	50
	_
	-
10	
PCM distance (km)	10
	-
ag0	-
0.5 1 PCA distance (km)	1.5
	_
000000000000000000000000000000000000000	-
100	150
Wind speed (km/h)	100
	-
	-
300 400 500	600
SWH (cm)	
	-
	3
00	-
0.1 0.15 Standard Deviation of M2 (m)	0.2
	-
	_
25 30	- 35
Nb data	55
	-
	-
200	300



Figure 8. T/P and tide gauge sea level variations at Capraia from *Vignudelli et al.* (2000).