Preliminary comparison of the TOPEX and POSEIDON-2 Radar Altimeters

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Abstract :

Taking advantage of the flying formation JASON-1, TOPEX/POSEIDON satellites (both on the same ground track and separated by 60 seconds), a preliminary performance comparison of their operational radar altimeters, respectively POSEIDON-2 and TOPEX, has been carried out.

After recalling the features of each altimeter, the comparative procedure is presented. It is mainly focused on the fact that the TOPEX data has been re-processed using the same ground retracking as the one used for the POSEI DON-1 data. Such procedure has been already used in the past with success (validation of the ENVI SAT radar altimeter ground processing). The major ouputs of this processing are the precise range, the significant wave height and the backscatter coefficient at the rate of the input waveforms (10 or 20 Hz). From these outputs one can then derive the 1 Hz parameters and the associated standard deviations.

The results we present are issued from the analysis of a few passes of data. They range from point by point comparison, to statistical analysis and noise characterization of the instruments. It is shown that both altimeters are in agreement and measure the same signal. It is also shown that they have about the same level of accuracy. These conclusions will be fully assessed in the future by performed this analysis over a larger set of data.

In parallel we are conducting an identical comparison using the POSEI DON-2 retracker. All the process is currently under validation. Finally, with the inclusion of the POSEI DON-1 data and the focus on JASON-1 cycles 17, 18, 19 and TOPEX/POSEI DON cycles 360,361,362, we will be able to have a full comparison of the three radar altimeters.



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1 TOPEX and POSEIDON-2 Major Features (Ku band)

TOPEX

Frequency : Pulse duration : Bandwidth : PRF : Waveform Samples : Sample resolution : Pulses number : Antenna Beamwidth :

Waveform Telemetry : On board tracker : range -AGC -SWH :

On board retracking : Ground retracking : No 13.60 GHz 102.4 μs 320 MHz 4200 128 3.125 ns or 46.84 cm 228 1.1°

64 samples at 10 Hz Adaptative windows α,β filter (0.25 and 1/64) α filter (0.3) on board, by ratio of power difference

No

POSEI DON-2

Frequency : Pulse duration : Bandwidth : PRF : Waveform Samples : Sample resolution : Pulses number : Antenna Beamwidth :

Waveform Telemetry : On board tracker : range - 90
1.34°
64 samples at 20 Hz Fixed windows
α,β filter (0.25 and 1/64)

3.125 ns or 46.84 cm

On board retracking : Yes Ground retracking : Yes (gain = 1)

Yes (gain = 1) = 1)

 α filter (0.5)

13.575 GHz

105.6 µs

1800

128

320 MHz

(Both retracking are based on a weighted Least Square Estimators derived from Maximum Likelihood Estimators using Hayne model for modelling the ocean return)

AGC -

CLS



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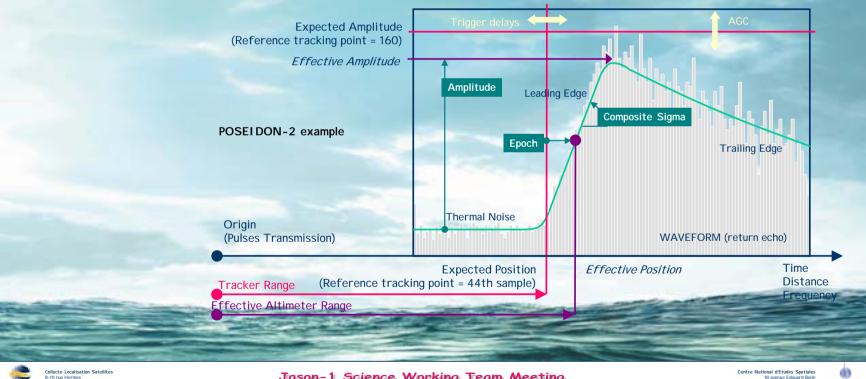
2 Tracker and Retracking (1/2)

Tracker :

The function of the tracker is to maintain the echo in the window analysis (range and power). When sophisticated as for TOPEX, the trackers plays also the role of the altimetric parameters estimator.

Retracker :

The function of the retracker is to extract the precise altimetric parameters (range, SWH, power)





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2 Tracker and Retracking (1/2)

Tracker Equations :

range $\begin{cases} h_n = h_{n-1} + r_{n-1} + \alpha * \varepsilon_{n-2} \\ r_n = r_{n-1} + \beta * \varepsilon_{n-2} \end{cases}$

 h_n is the estimate value of the range to be applied on cycle n r_n is the estimate value of the range increment to be applied on cycle n ϵ_n is the range error. It is determined by balancing the return power in fixed or adaptative windows, accounting for an ocean echo model (Brown or Hayne) α and β are the first and second order loop coefficient

AGC : first order loop (very closed to the top one equation)

Retracking equations (iterative solution):

$$\begin{cases} \theta_{k,n} = \theta_{k,n-1} + g * (BB^T)^{-1} BD \\ B_{k,i} = \frac{1}{P_u} \frac{\partial \overline{V}_i}{\partial \theta_k}, D_i = \frac{\overline{V}_i - V_i}{P_u} \end{cases}$$

 $\begin{array}{l} \theta_{k'n} \text{ is the estimate value of the altimetirc parameter (range, SWH, power)} \\ \text{ at iteration n} \\ \text{g is the gain} \\ P_u \text{ is the estimate of the power} \\ V_i \text{ is the theoretical sample based on an ocean echo model (Brown or Hayne)} \\ V_i \text{ are the samples from the measured echo radar} \end{array}$

The retracking of POSEI DON-2 and POSEI DON-1 differs by : - estimation of SWH for POSEI DON-1 instead of SigmaC for POSEI DON-2 - criteria convergence

Altimetric parameters equations The accurate altimetric estimates are given by :

Altimeter Range Backscatter Coefficient Significant WaveHeight

- = Tracker Range + Epoch (0 without retracking)
- = «Radar equation» + AGC + Amplitude (about 160 without retracking, reference power)
- = 2c.Sqrt (SigmaC**2-SigmaP**2), SigmaP = PTR width or directly from the retracking (POSEI DON-1 retracking), or by the ratio of the difference of energy (TOPEX)

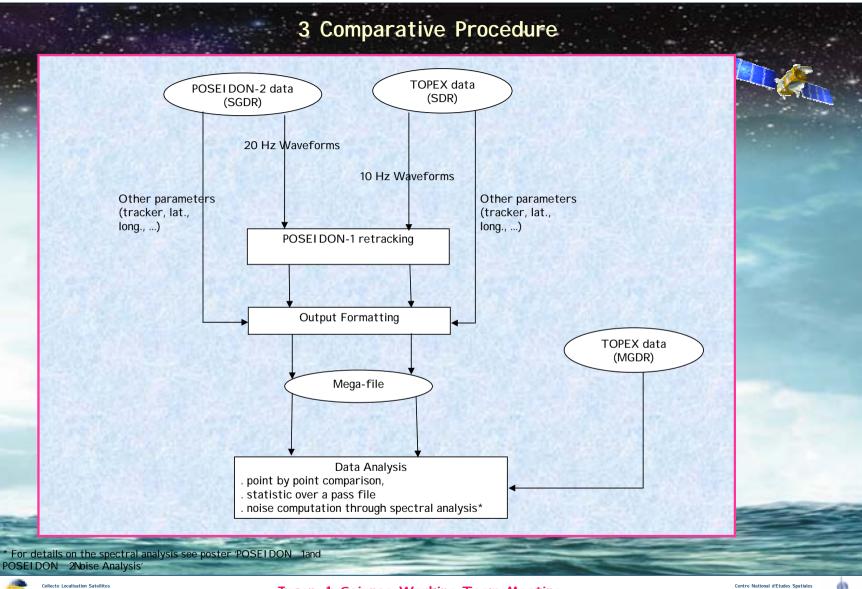


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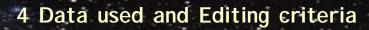


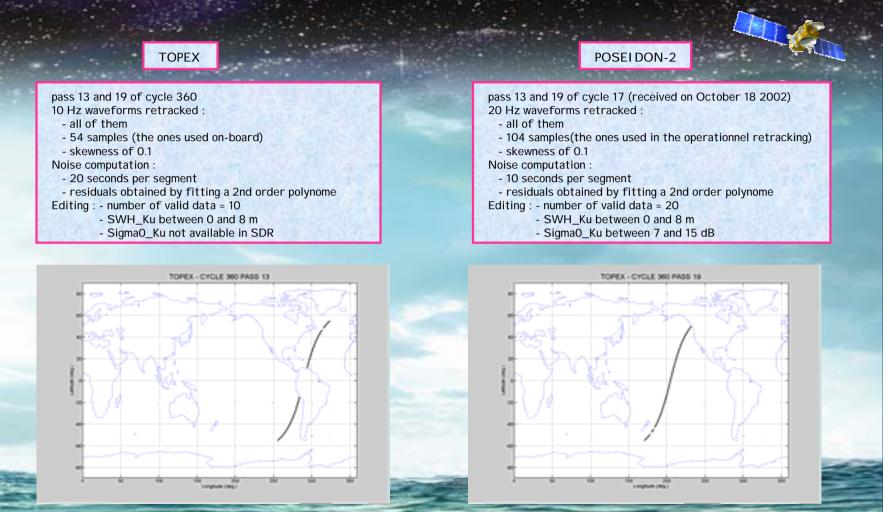




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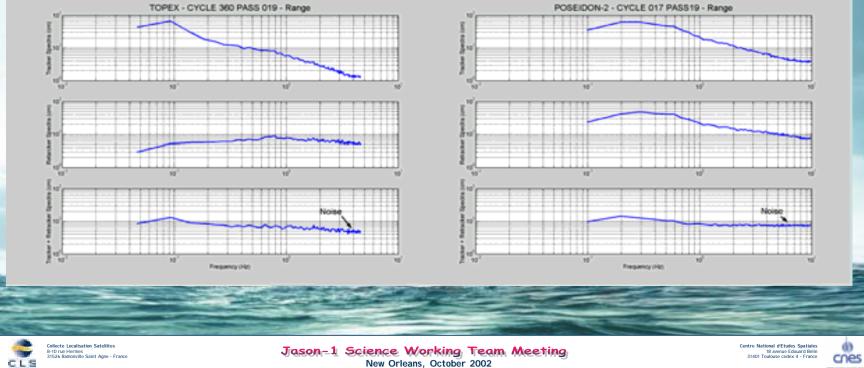


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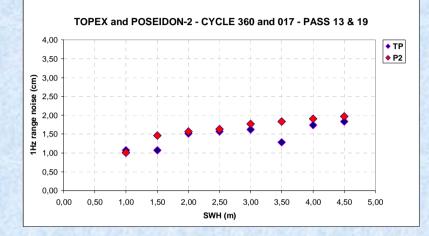








5 Noise from Spectral Analysis (2/2)



The noises are computed at 1Hz using the decorrelation assumption (division of the 10 or 20 Hz noise by square root 10 or 20). For SWH = 2 m the values are :

- TOPEX : 1.52 cm - POSEI DON-2 : 1.56 cm

For SWH, the values at 2m SWH are :

- TOPEX : 9.83 cm - POSEI DON-2 : 12.88 cm

These values can be considered as identicaldue to the low number of passes

Conclusions

TOPEX and POSEI DON-2 waveforms have been retracked using the same retracking (POSEI DON-1) as well as quasiidentical conditions of retracking. A couple of passes have been analysed and the preliminary noise figures indicate that both altimeter give the same answer, which is for a SWH of 2 m :

1.5-1.6 cm for the 1Hz range noise **10-12 cm** for the 1Hz SWH noise.

These results are preliminary and need to be confirmed, nevertheless one can start guessing that the radar altimeters will be very close one to each other. In the future, POSEIDON-1 will be included in this comparison.



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