

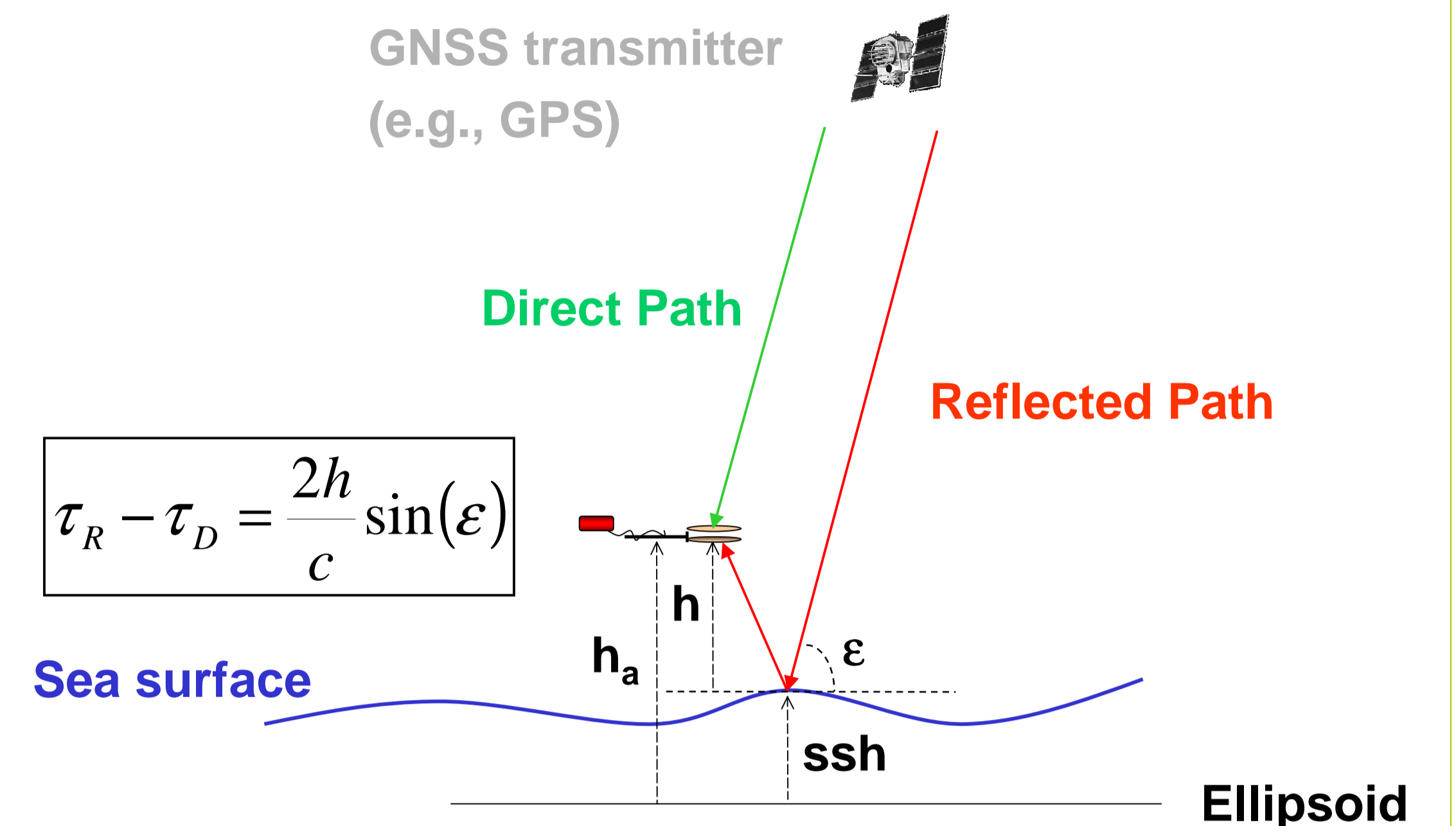
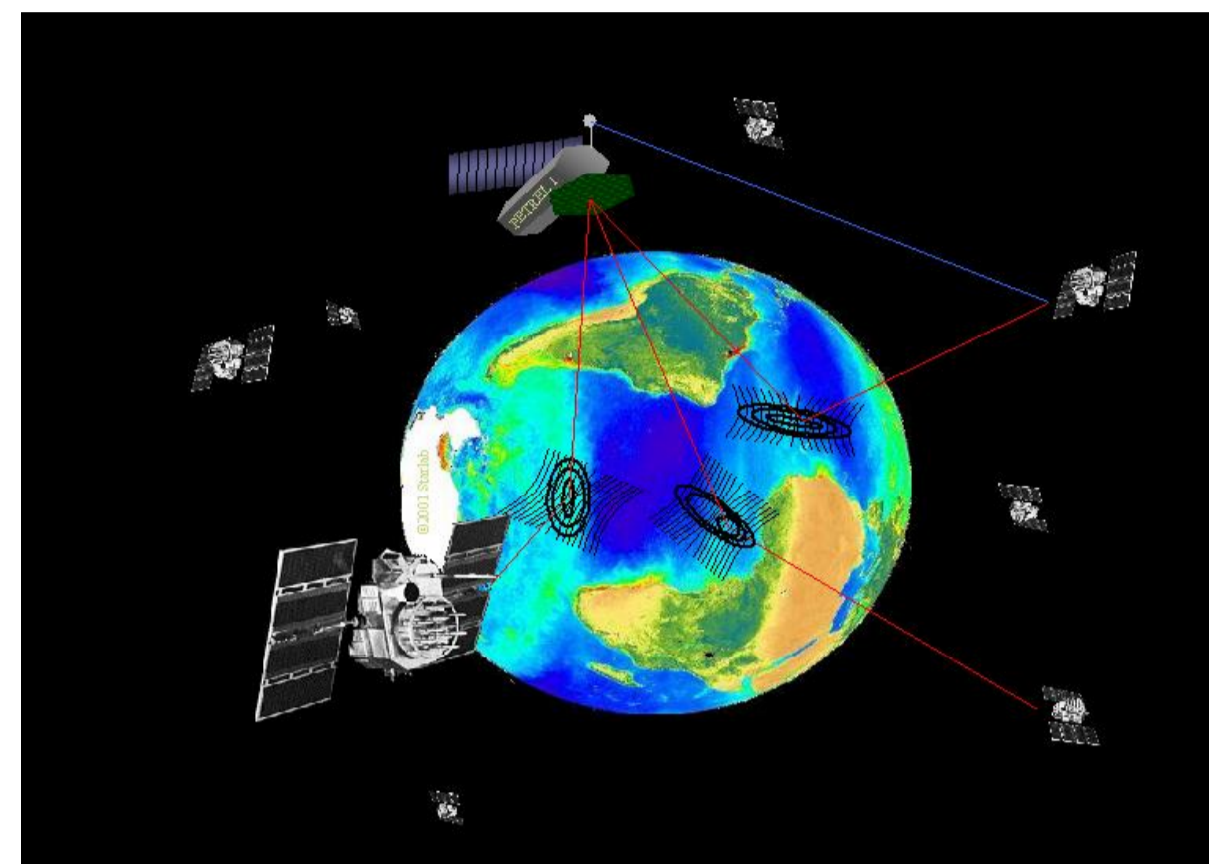
Airborne Sea-Surface Altimetry with GPS Reflections

O. Germain, G. Ruffini, M. Caparrini, F. Soulat *
 Starlab, C. de l'Observatori Fabra s/n, 08035 Barcelona, Spain, <http://starlab.es>

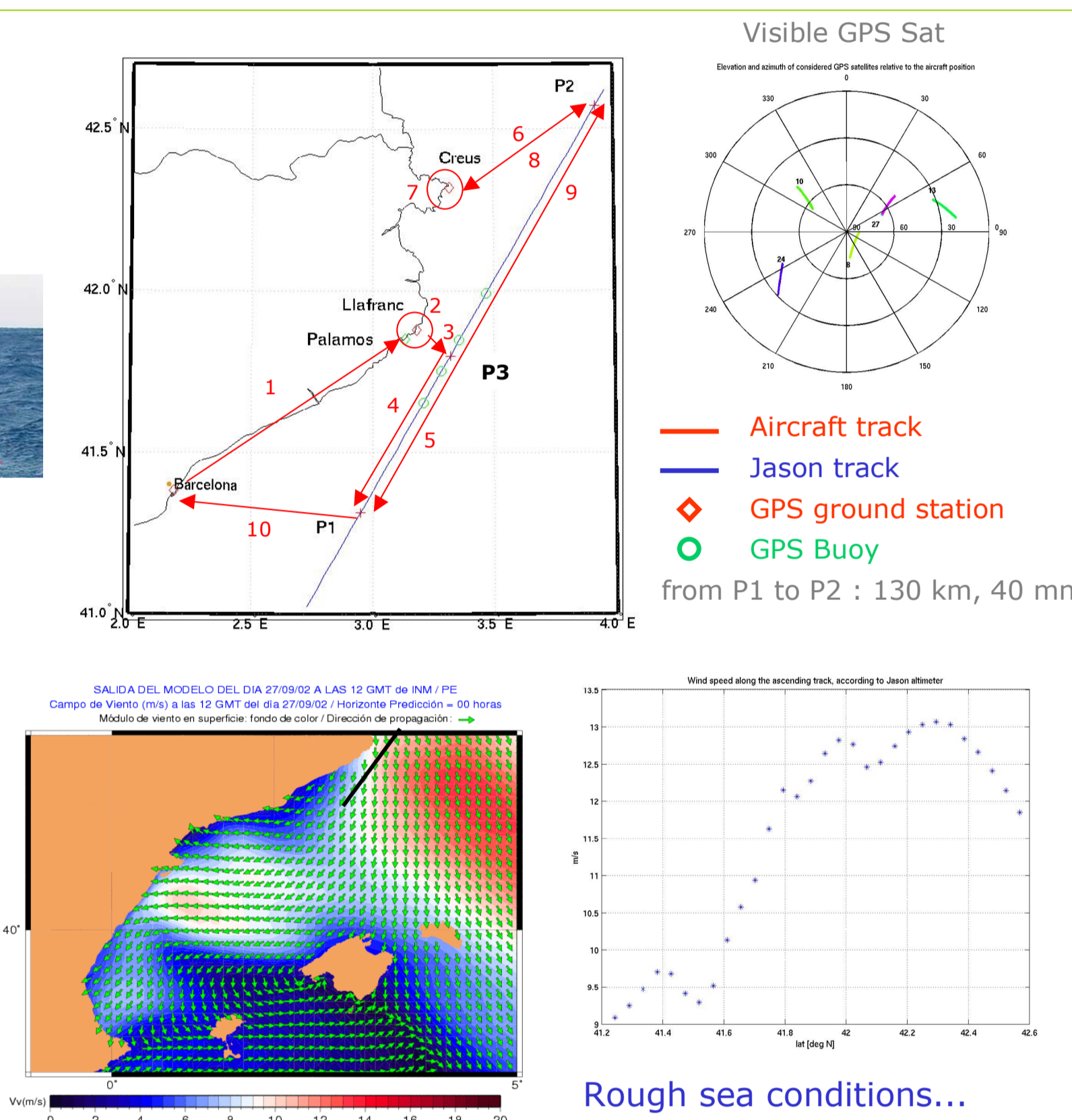
M. Martin-Neira
 ESA/ESTEC, Keplerlaan 1, 2200 Noordwijk, The Netherlands, <http://esa.int>

Context and Concept

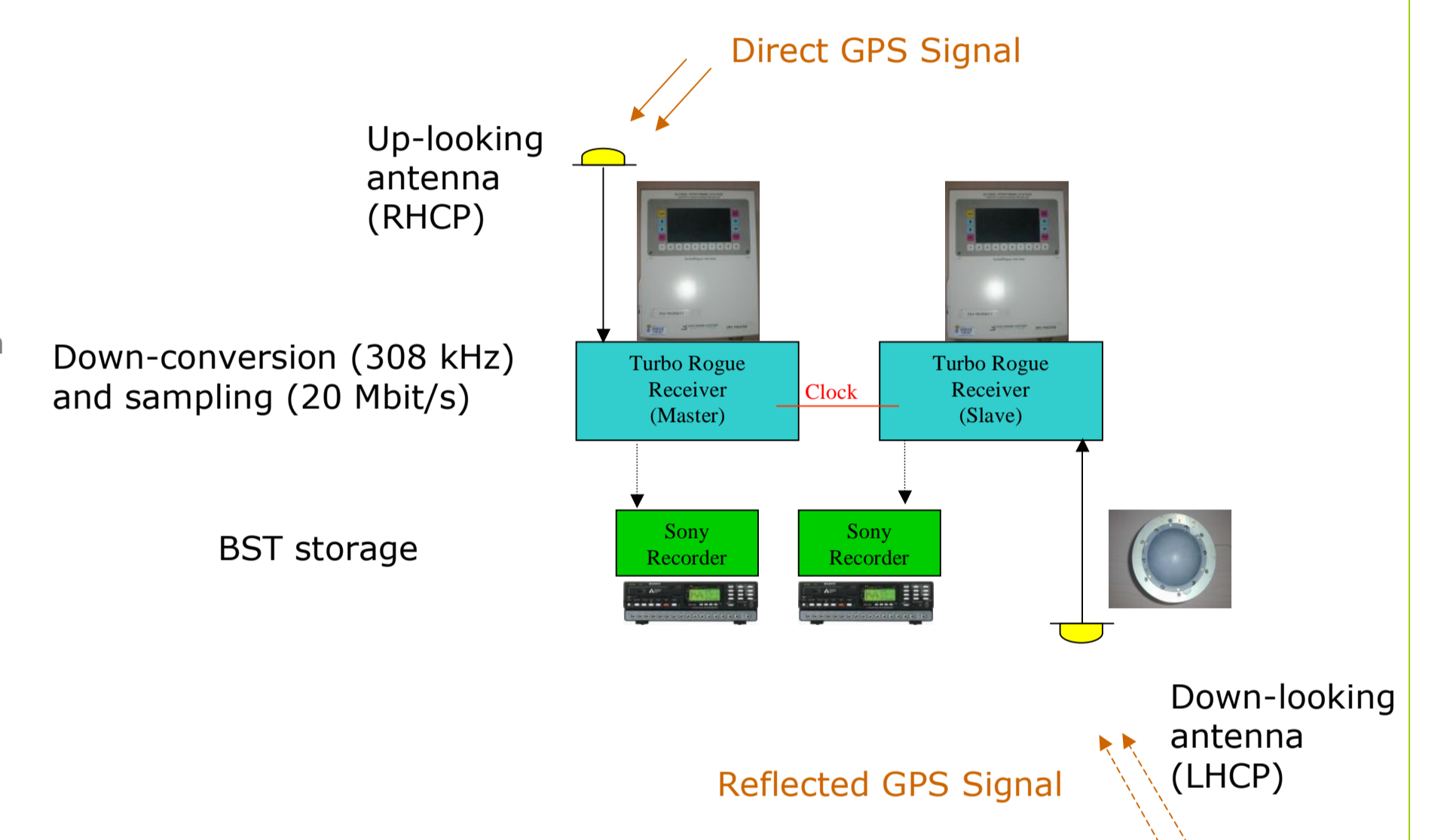
- Under ESA contract PARIS-GAMMA Phase-1 (TRP ETP 137.A)
- Development of technologies for sea-surface mesoscale altimetry with GNSS reflected signals (GNSS-R)
- Demonstrate GNSS-R airborne C/A code altimetry
- Provide a precise reference for a potential future space mission



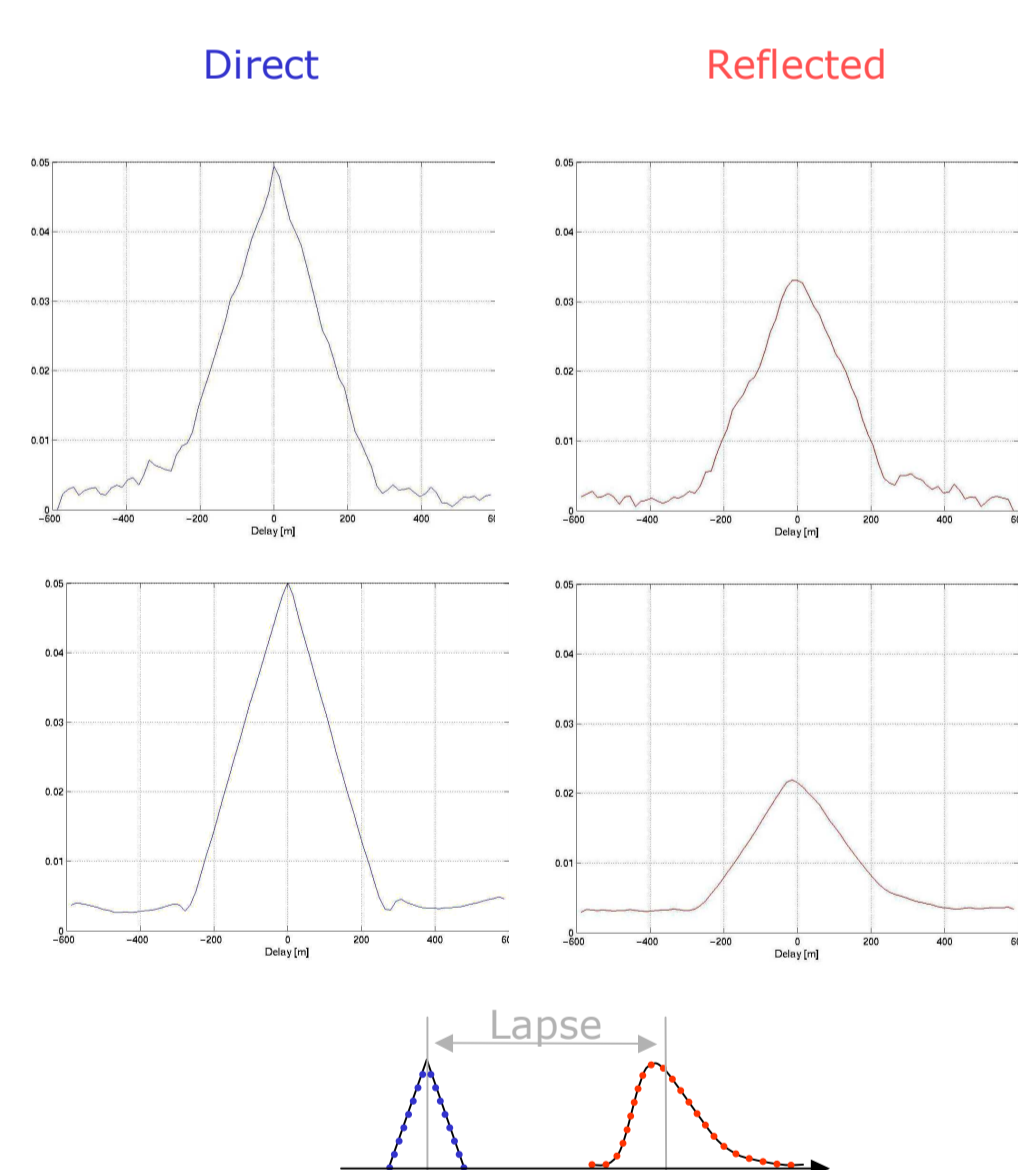
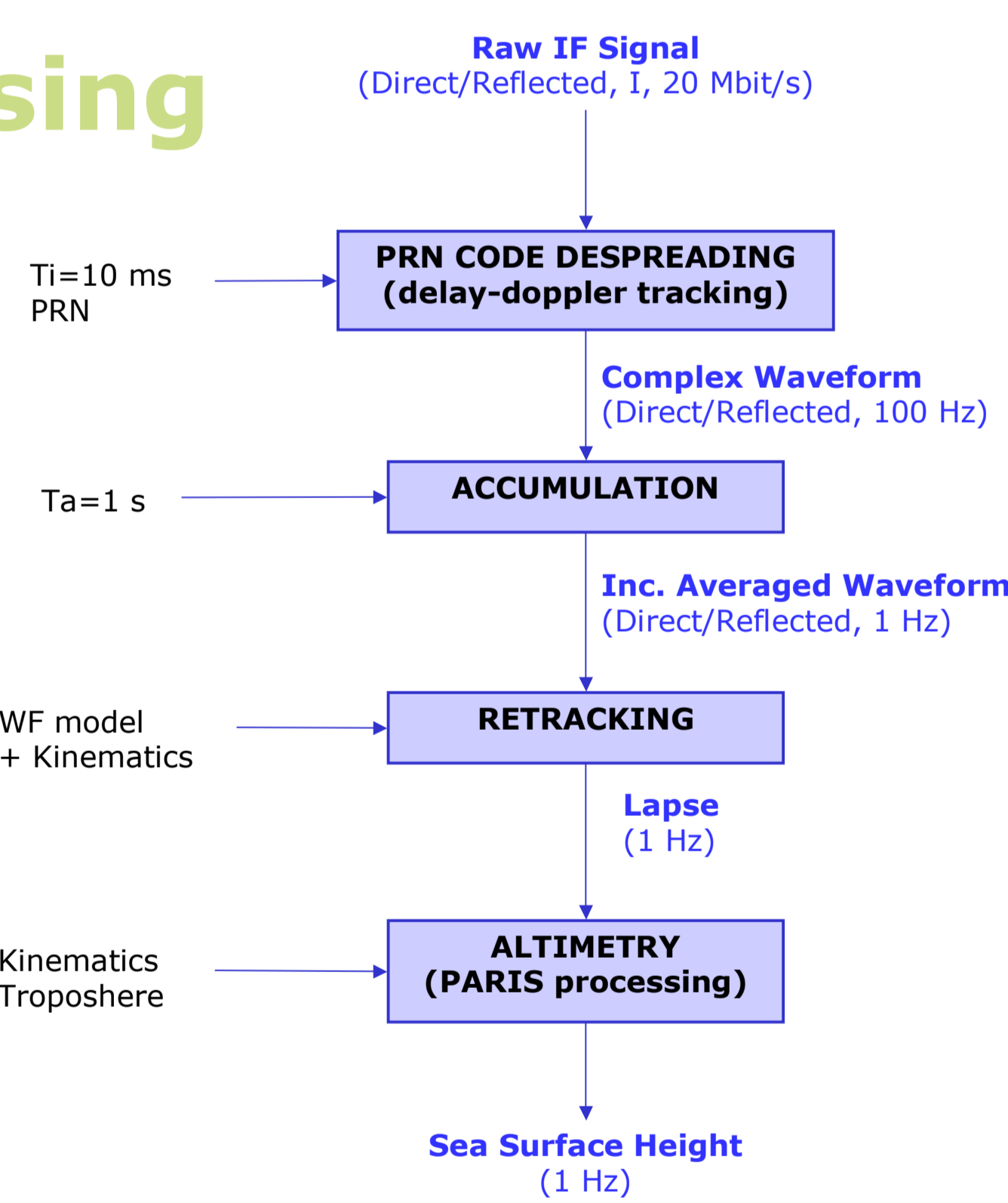
- Catalunya coast, 27th September 2002
- Aircraft @ 1 km altitude, 50 m/s speed
- Acquisition of raw direct/reflected L1 GPS data
- GPS station network + INS for precise kinematics
- Ground truth: JASON + buoys data



The Experiment



Processing

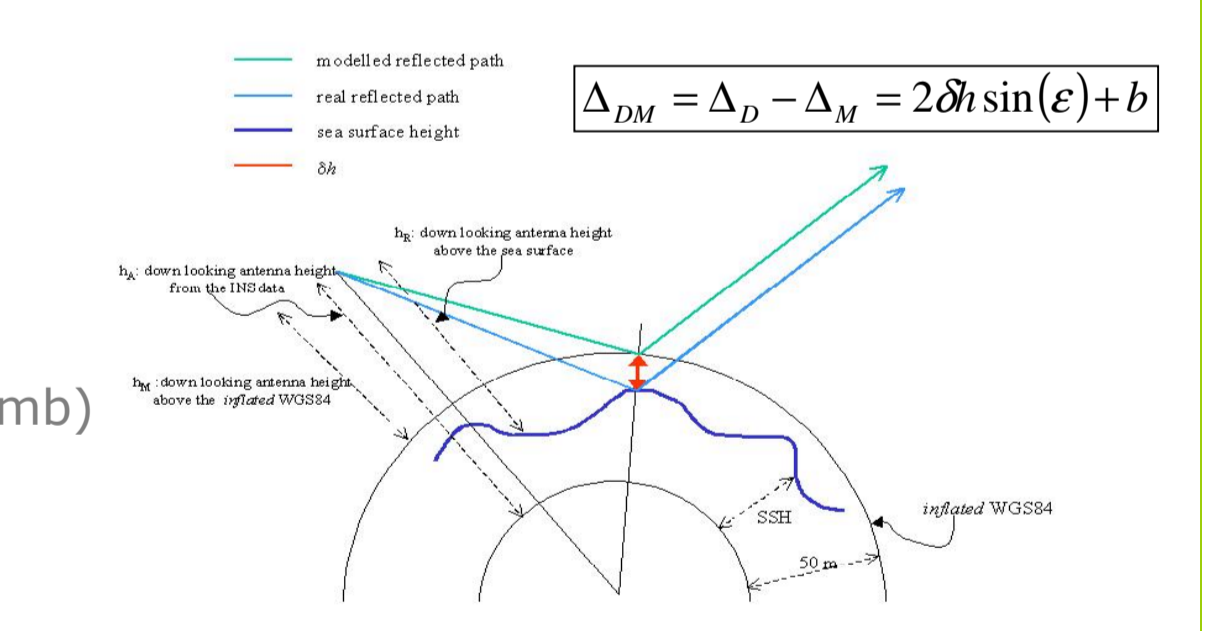
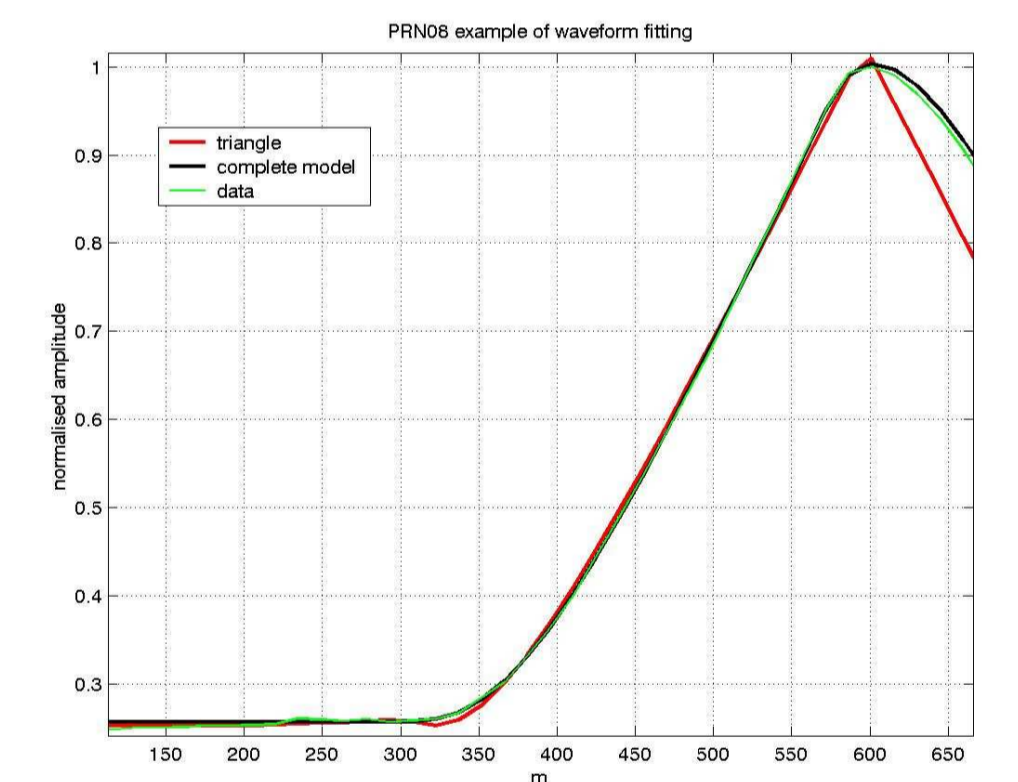


RETRACKING

- Waveform model:
 - Direct: PRN autocorrelation
 - Reflected: Bistatic Radar Equation (Kirchoff+GO)
- Numerical Optimization:
 - Steepest slope descent algorithm
- Parameters:
 - delay, scaling factor
 - SWH (but irrelevant)
 - directional sea-roughness (3 DMSS)
 - antenna rotation (known up to some degrees)

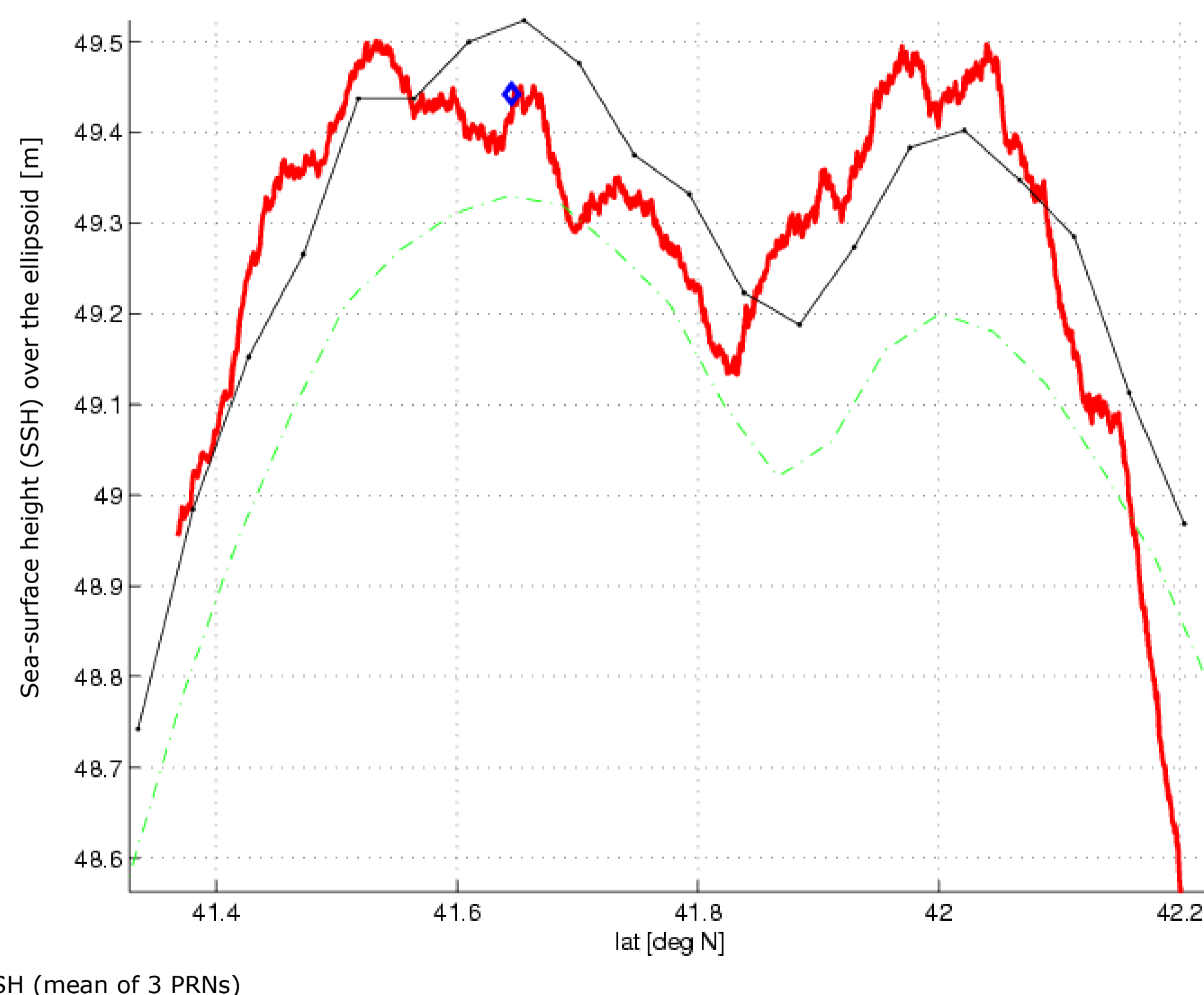
ALTIMETRY

- Differential version of the PARIS equation
- Atmospherics:
 - Ionosphere delay cancels out in airborne GNSS-R
 - Troposphere does not. Components are dry and wet
 - Dry easily estimated using surface level pressure (1024 mb)
 - Wet estimated from SSM/I data, agrees with GPS
 - Correction applied to the lapse: 60 cm/sin(elev) (±5 cm)



Altimetric results filtered @ 200 s (10 km) obtained with the following assumptions:

- wind speed 10 m/s
- wind direction: North
- SPI = 0.65
- antenna rotation = 220 deg



Results

CONCLUSION

- The Eddy Experiment can be considered a success:
 - Precision after one-second: around **3 m** (lapse RMS for each PRN)
 - Accuracy w.r.t. Jason SSH: around **10 cm** (mean of 3 PRNs)
- We believe this represents a significant step along the GNSS-R road.

RECOMMENDATIONS AND PERSPECTIVES:

- Future experiments needed at higher altitudes (5 to 10 km). Low altitude flights represent the worst case scenario:
 - severe sea-roughness (DMSS) impact
 - multipath in reflected signal
- Sensitivity to antenna pattern. Needs to be precisely calibrated
- A PARIS Aircraft Demonstrator (PAD) is now being built (PARIS-GAMMA Phase-2).
 - multi-beam system with on-board signal processing
 - design seeks to minimize the space risk.

* All Starlab authors have contributed significantly; the Starlab author list has been ordered randomly