## **Incidence Angle Dependence of EM Bias**

Karl F. Warnick, Floyd W. Millet and David V. Arnold Department of Electrical and Computer Engineering Brigham Young University

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# Hydrodynamic modulation





## Wide-swath altimeter









Simple hydrodynamic model [Melville and Felizardo, 1999]:

$$h_s(\eta) = h_s(0) \left[ 1 + S \eta / h_l \right]$$

where S is RMS long wave slope,  $h_s$  is small wave surface height standard deviation, and  $\eta$  is displacement from mean sea level.

Physical optics scattering from tilted/modulated surface facets

Bias(
$$\theta$$
) =  $\frac{E[\eta \sigma_0(\theta)]}{E[\sigma_0(\theta)]}$ 



BYU Off-Nadir Experiment (Y-ONE)
March-April 2003
Gulf of Mexico, Shell Offshore platform
C, Ku band Doppler radars, laser rangefinder
Environmental data including wind, temp
Incidence angles: -3° to 17°, 5 minutes/angle





## Results



Incidence Angle vs. EM Bias, YONE 5 SWH = 0.5mMean Values SWH = 1mSWH = 1.5mSWH = 2m0 0 EM Bias (cm) EM Bias (cm) -5 -2-3 -10<u>-</u>0 5 10 15 20 2 10 12 16 0 4 6 8 14 Incidence Angle (<sup>o</sup>) Incidence Angle (°)

Predicted bias

Experimental measurements Error bars are ± one sigma Mean significant wave height: SWH = 0.9m (results are preliminary)





#### Time series - SWH





## Bias vs. significant wave height







#### Relative bias vs. RMS slope





## Summary/Conclusions



- Experimental measurements and theoretical analysis predict decrease in EM bias as incidence angle increases
- Mean EM bias may change sign at mid-range incidence angles
- Wide-swath instruments may require incidence-angle dependent correction
- Multiple looks at a given surface footprint at different incidence angles may be used to improve bias correction