

Which duration for the Jason-2 / Jason-1 repeat-track phase?

- Verification and Cal/Val purposes
- Applications and operational needs

J. Dorandeu - CLS

Introduction (1/4)

- Objectives of the verification phase:
 - To ascertain that the overall **altimeter System** (including all components: sensors, platform, orbit calculation, ground processing...) complies with its **specifications**, and fulfils the mission requirements. Thus the primary objective is to **compare the actual error budget to the specified one**.
 - To fulfill users' needs (this objective stretches over the whole mission lifetime) :
 - The main users' needs have been translated into system requirements (specified error budget)
 - **1 mm/yr** error in the MSL estimation at global scale is only a **goal, not a specification** and, as shown in the recent years, the MSL problem is now more on local estimates (few mm/yr at local scale)
 - It is the **strength of the OSTST** for many years **to enlarge mission objectives, to refine the needs** and consequently to require **more and more accuracy**: climate change studies are the more demanding in terms of stability , even at local scale.

Introduction (2/4)

OSTM/JASON-2 Science and Operational Requirements (Menard, Fu, Lambin, Bonnekamp, Lillibridge, ref: TP3-J0-SP-188-CNES)

- Scientific Objectives and Requirements:
 - Mean Dynamic Topography
 - Intra-seasonal to inter-annual variability
 - Mesoscale and coastal oceanography
 - Mean Sea Level trend
 - Marine meteorology
 - Inland studies
 - Geophysics and geodesy
- Operational Applications and Requirements
 - Short and mid-term applications: mesoscale, coastal applications, climate applications
 - Near Real Time applications: marine meteorology and other NRT applications
 - CalVal activities and oceanographic campaign

Introduction (3/4)

Both Science and operational requirements have been translated into the overall error budget (OSTM/Jason-2 system, TP3-J0-STB-44-CNES by Perbos, Parisot, Vaze, Bannoura):

C	OGDR 3 hours	IGDR 1 to 1.5 days	GDR 40 days	GOALS
Altimeter noise	2.5 (a)(c)(d)	1.7 (b)(c)(d)	1.7 (b)(c)(d)	1.5 (b)(c)(d)
Ionosphere	1 (e)(d)	0.5 (e)(d)	0.5 (e)(d)	0.5 (e)(d)
Sea State Bias	3.5	2	2	1
Dry troposphere	1	0.7	0.7	0.7
Wet Troposphere	1.2	1.2	1.2	1
Altimeter range RSS	5	3	3	2.25
RMS Orbit (Radial component)	10 (h)	2.5	1.5	1
Total RSS sea surface height	11.2	3.9	3.4	2.5
Significant wave height	10% or 0.5 m (i)	10% or 0.4 m (i)	10% or 0.4 m (i)	5% or 0.25 m (i)
Wind speed	1.6 m/s	1.5 m/s	1.5 m/s	1.5 m/s
Sigma naught (absolute)	0.7 dB	0.7 dB	0.7 dB	0.5 dB
System drift				1mm/year (j)

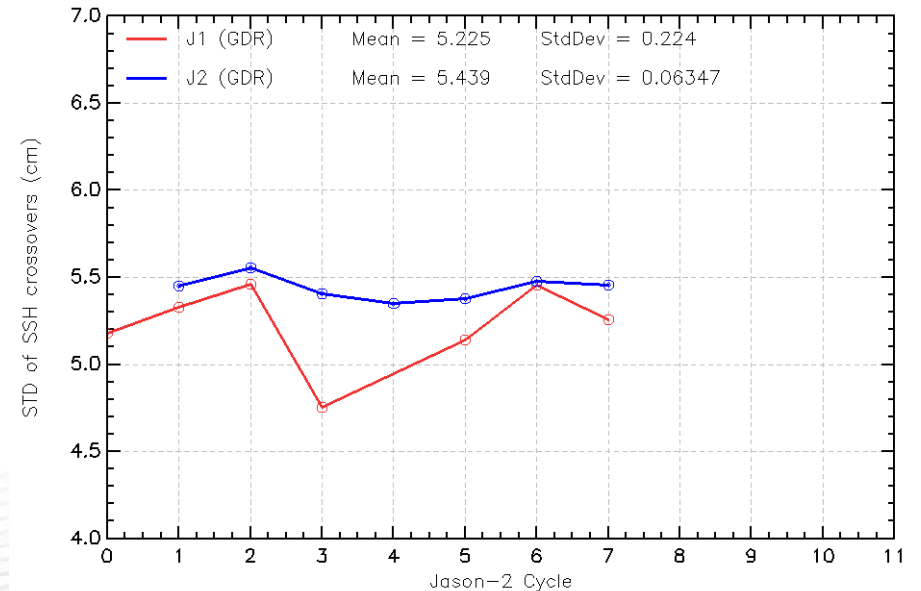
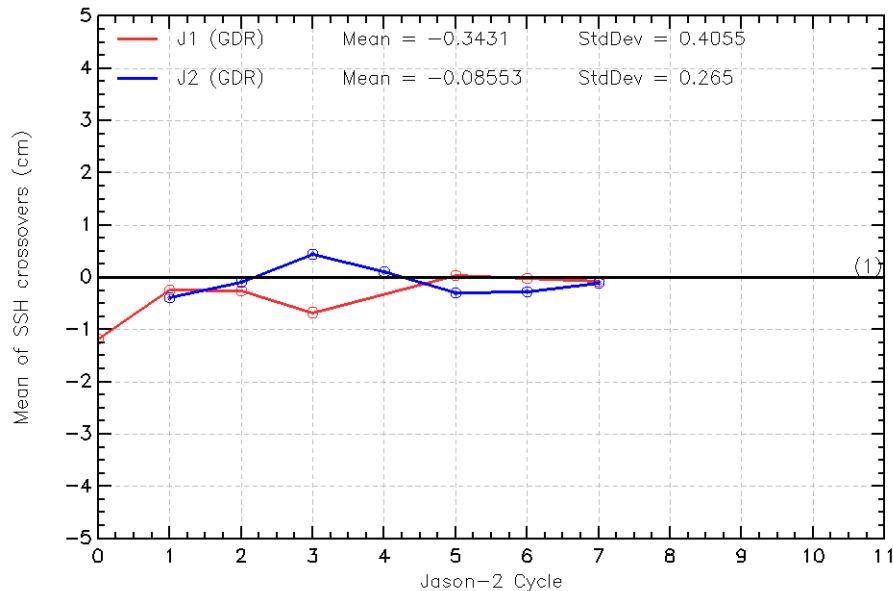
- (a) Combined Ku + C measurement
- (b) Ku band after ground retracking
- (c) Averaged over 1 sec
- (d) Assuming 320 MHz C bandwidth
- (e) Filtered over 100 Km
- (f) Can also be expressed as 1% of H1/3
- (g) After ground retracking
- (h) Real time DORIS onboard ephemeris
- (i) Which ever is greater
- (j) On global mean sea level, after calibration

Introduction (4/4)

- A proposed trade-off objective for the verification phase in repeat-track configuration:
 - Ensure **compliance with error budget specifications** (minimum required)
 - Ensure that **further improvements** in J2 quality will be **possible** (ground processing, orbit calculation) and even using the repeat-track data
 - Establish **other efficient CalVal methods after** the exact repeat phase
 - Show that further **consistency** improvements between J1 and J2 would not necessarily improve **J2 quality** (intrinsic J1 errors, consistency of errors...)
 - Then **move as soon as possible to a new ground track** to improve time/space sampling by altimeter data for applications' needs (like operational oceanography)
- This outlines the following slides

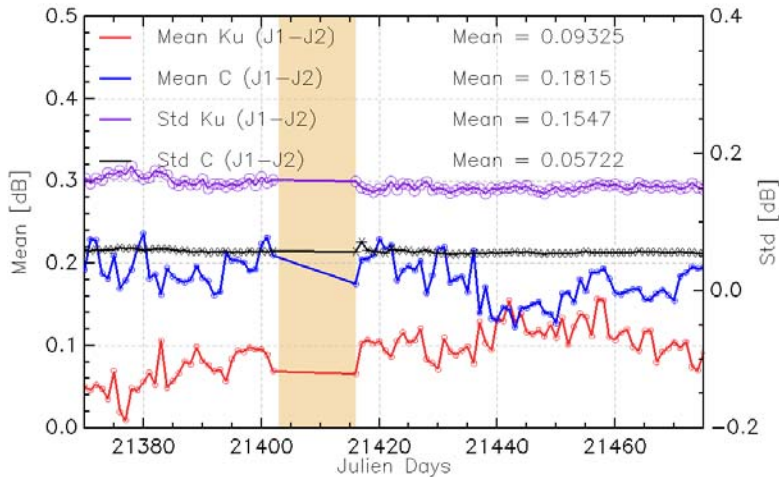
1. J2 SSH overall performances

- Very good SSH performances from crossover analysis
 - Though the Precise Orbit calculation is not yet completely tuned

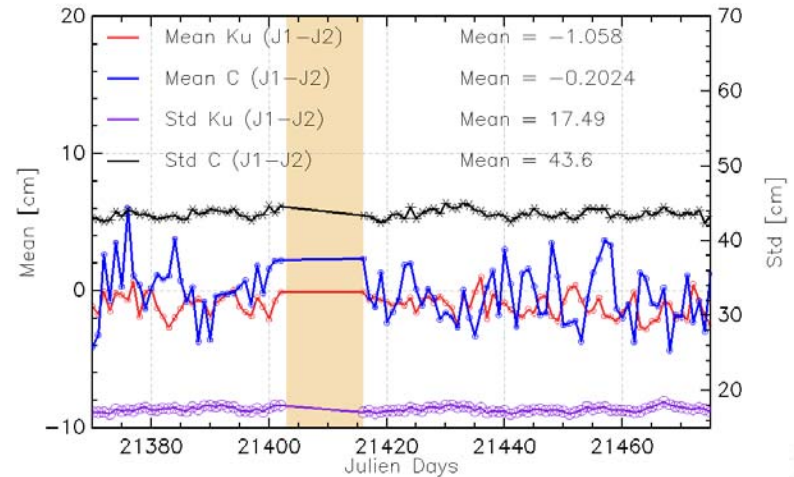


1. J2 overall performance

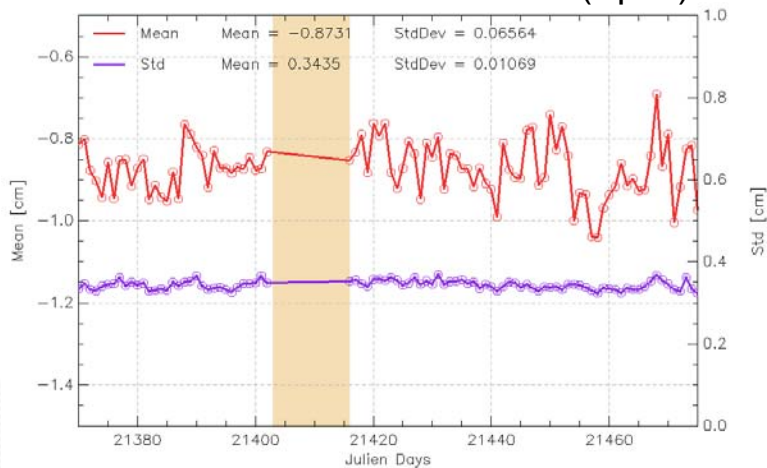
ΔSigma0 : 0.15 dB RMS / 0.7 dB (Spec)



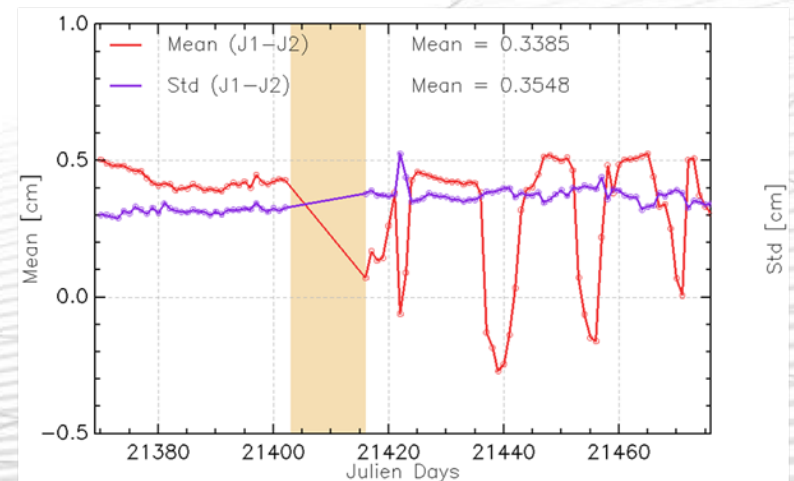
ΔSWH : 15.5 cm RMS / 40 cm (Spec)



Δlon0 : 3.4 mm RMS / 5 mm (Spec)

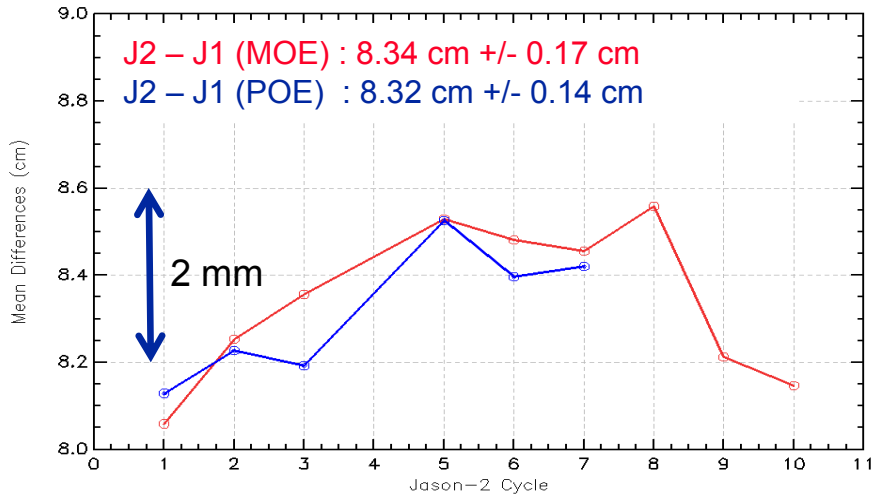


$\Delta\text{tropo} \sim 5$ mm due to Jason-1

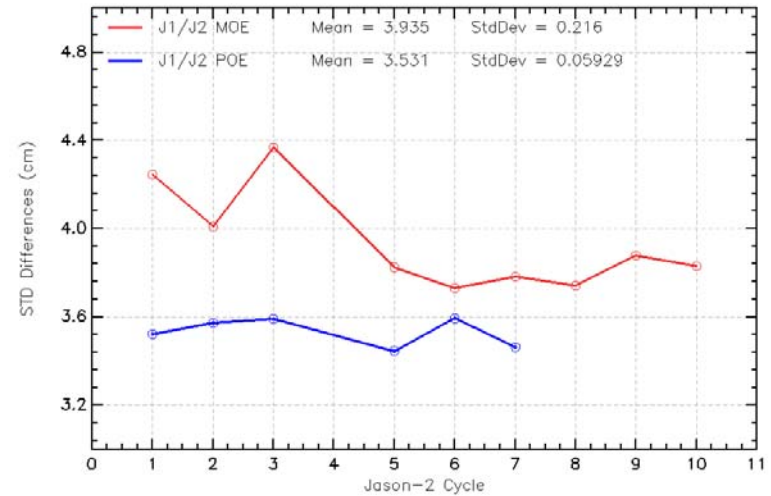


J2 SSH performance and Consistency relative to J1

J2 – J1 mean differences



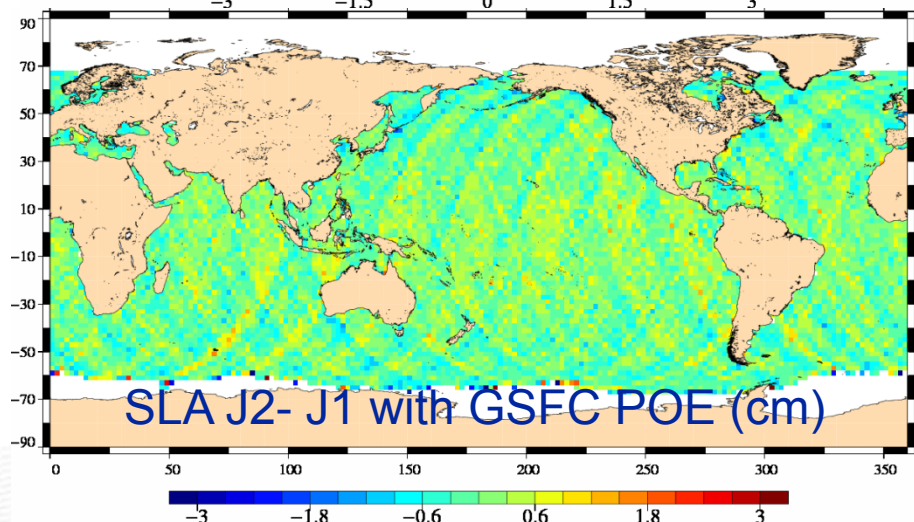
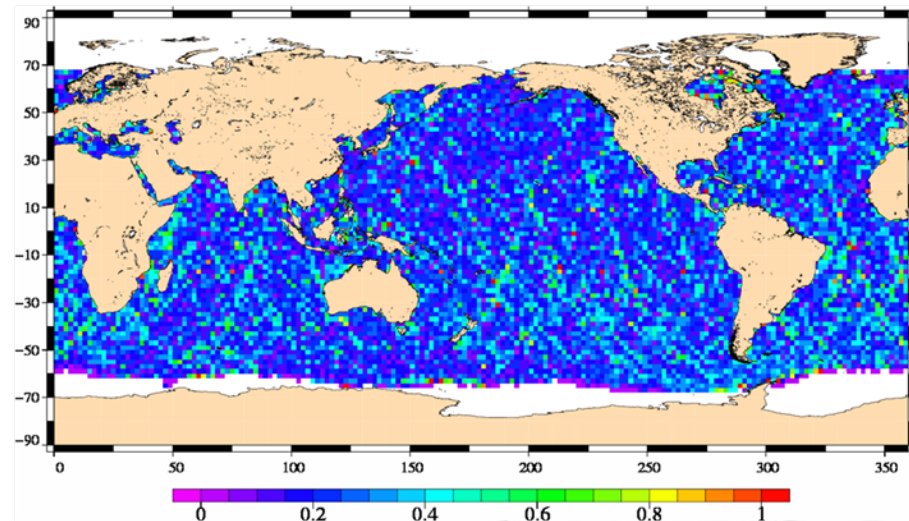
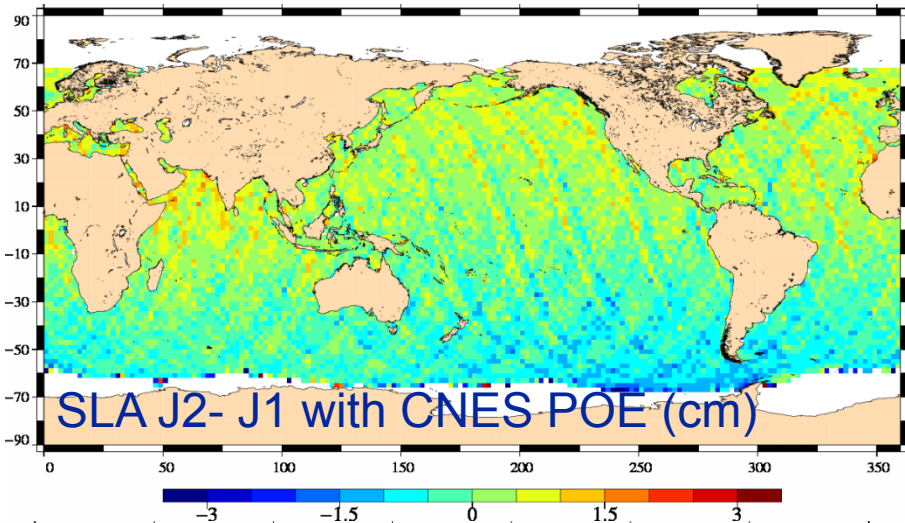
(J2 – J1) Std



3.5 cm RMS to be compared to $3.4 \times \sqrt{2}$ (spec)

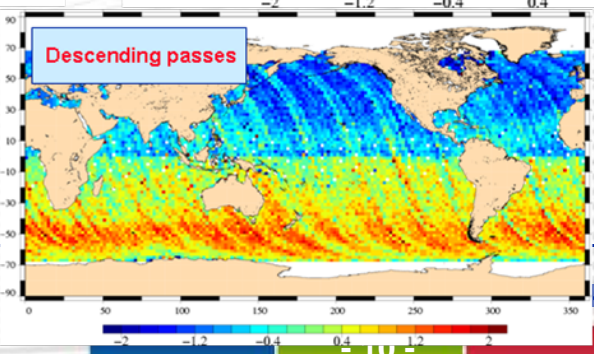
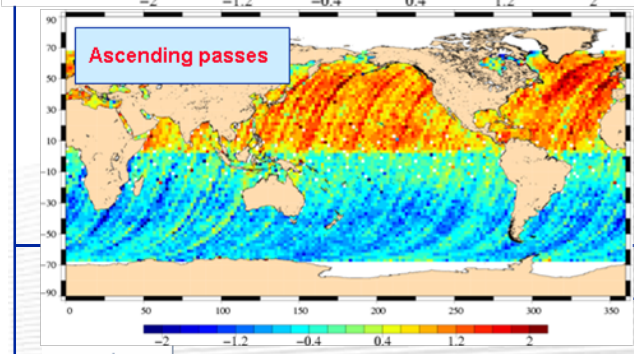
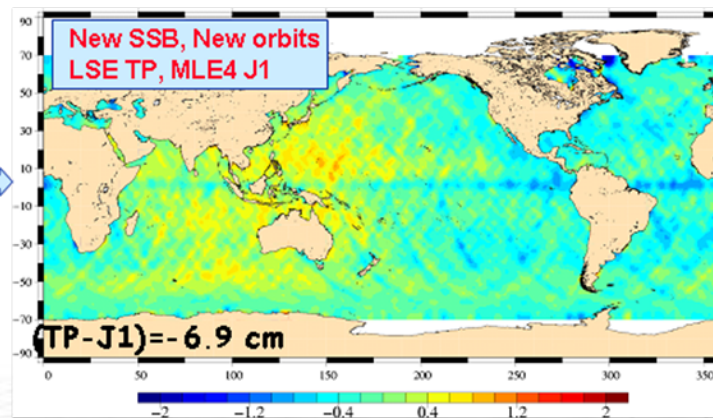
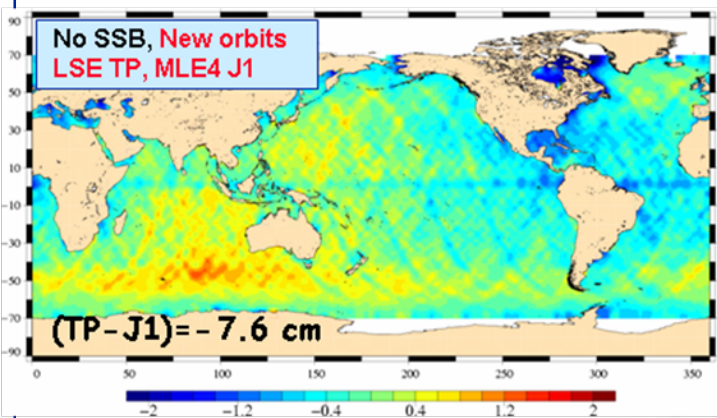
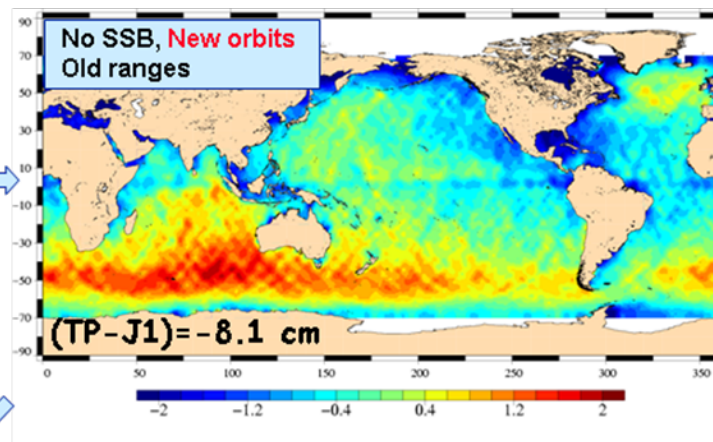
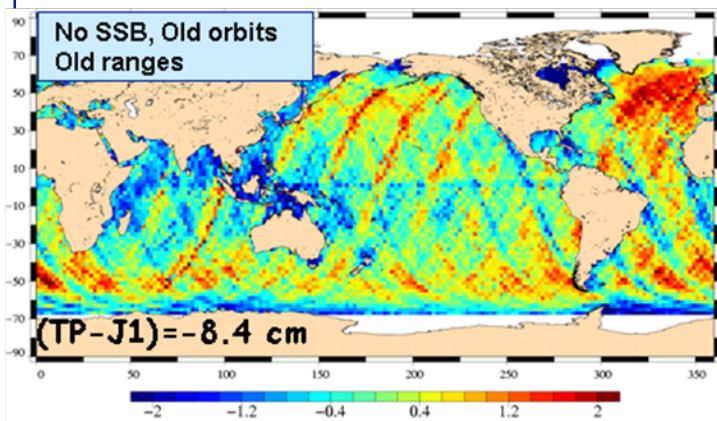
J2 / J1 geographically correlated errors

(main issue between J1 and T/P during J1 verification phase)



- Local differences accumulated over 6 cycles (POE orbit)
- Mean differences locally reduced to less than 5 mm (left figure)
- Local differences are constant: Std. Dev ~ 2 mm RMS

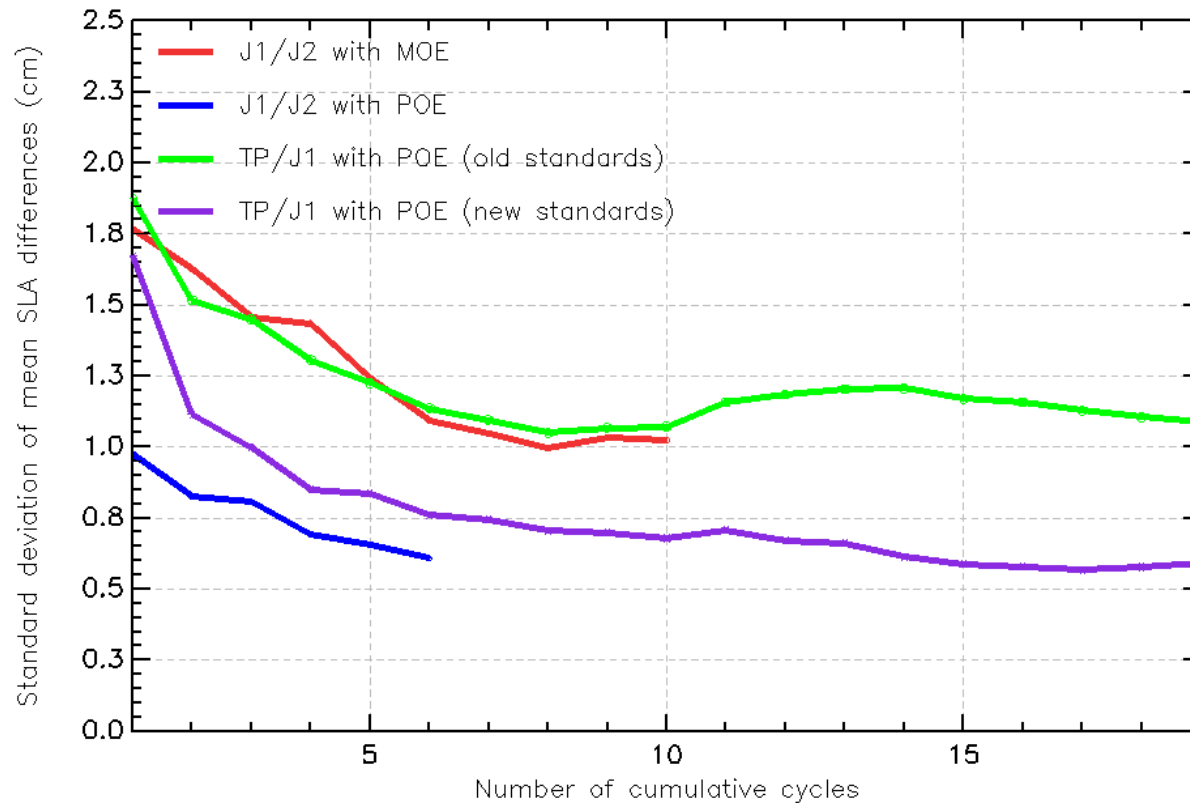
Comparison with the former J1/ T/P differences



- Local differences accumulated over 21 cycles
- Improvements carried out after the shifting the T/P track
- Orbit calculation impact: Grace gravity fields
- Retracking impact (T/P)
- SSB impact
- Retracking of the whole TOPEX dataset will improve the continuous precise altimeter series

10 phase duration

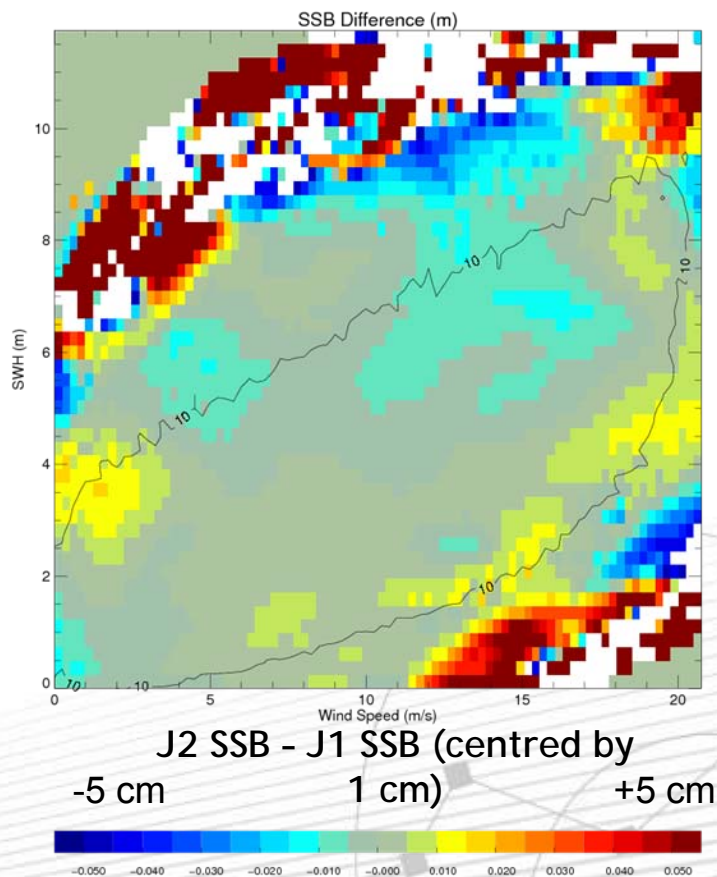
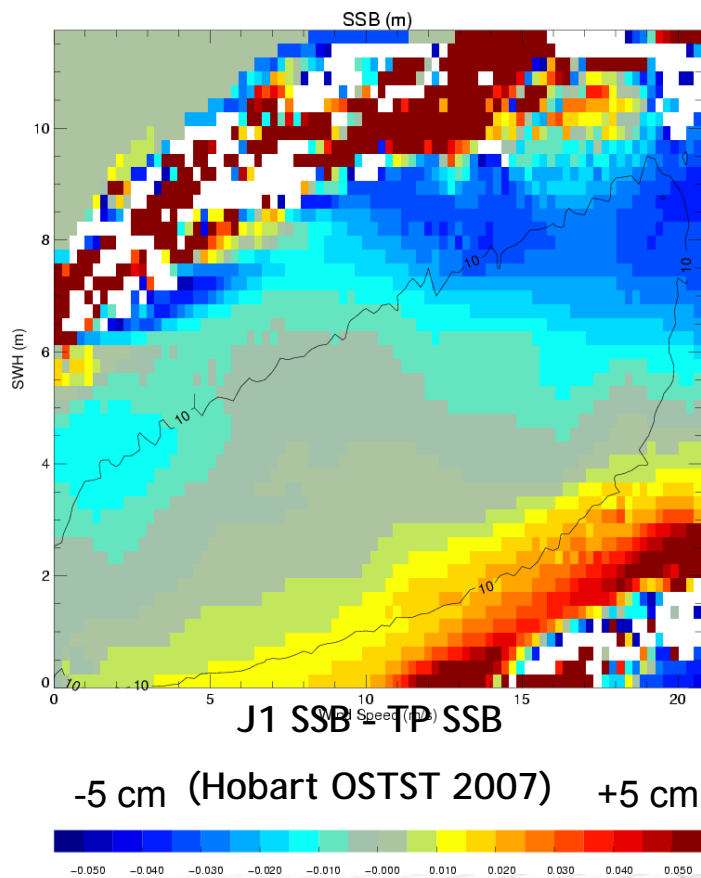
Geographically correlated differences



- Maps of differences computed over different periods (accumulating data in the local average)
- Std. Dev. computed among geographical bins (estimate of map homogeneity)

J2 / J1 SSB difference (Labroue, S.)

(was one of the main sources of differences between T/P and J1)



With only four months of data (J2-J1), we are at the same level of agreement than between J1 and TOPEX after 6 years of studies

Summary of main CalVal results

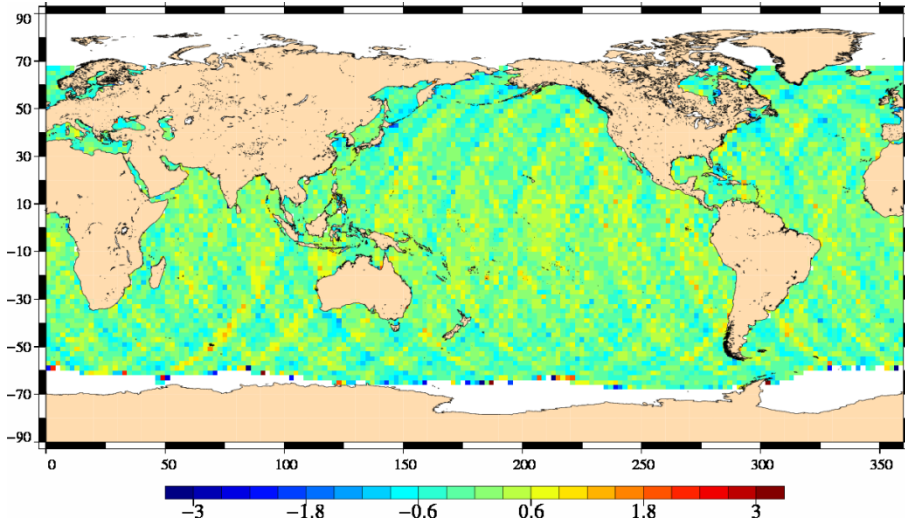
- Very good performances of the overall altimeter system:
 - altimeter OK
 - AMR performs better than JMR
 - Impressive MOE and POE results (even preliminary)
 - No issue detected from CalVal analysis. Fully compliant to specified error budget
- After 4 months, very good SSH consistency between J1 and J2
 - differences are lower than 0.5 cm and constant
 - as good as between J1 and T/P with 9 months of data and a lot of studies carried out afterwards (2 years of continuous improvements)

Consistency / homogeneity vs absolute performance

- Do we have to ensure a perfect homogeneity between J1 and J2?
 - Consistency is already at a very good level (< 5 mm)
 - Continuity will be ensured between J1 and J2, better than between T/P and J1
 - Constraining J2 to fit J1 as much as possible could raise other concerns that could significantly impact the overall error budget:
 - AMR troposphere correction is improved relative to JMR
 - DORIS receiver is better on J2 than on J1(USO frequency, SAA), more GPS measurements in J2 orbit
 - J1 ageing has to be taken into account
 - Doing the same sometimes produces undesirable effects:
 - Experience from T/P / J1 verification phase: former standards (JGM3) were kept for consistency needs, while new gravity fields would have performed better (as demonstrated afterwards)

Consistency / homogeneity vs absolute performance

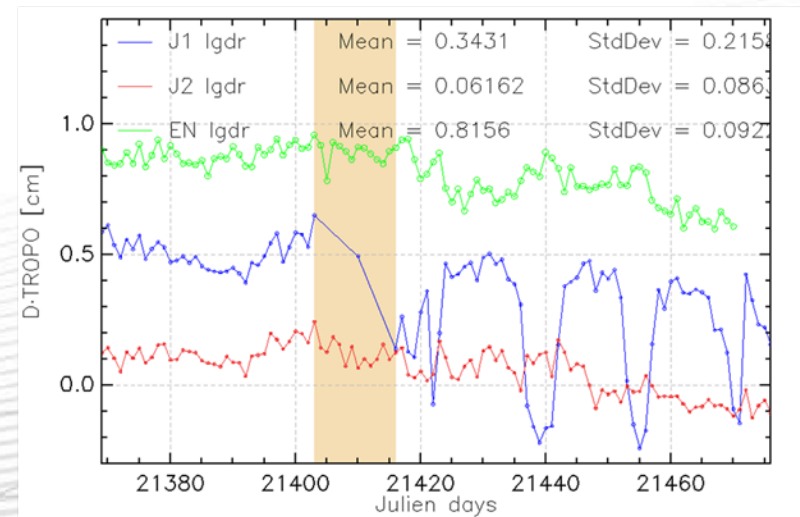
Mean (J2 – J1) differences (cm)



- Can we really improve much?

- Avoiding to propagate J1 errors on J2

differences between radiometer and model (cm)

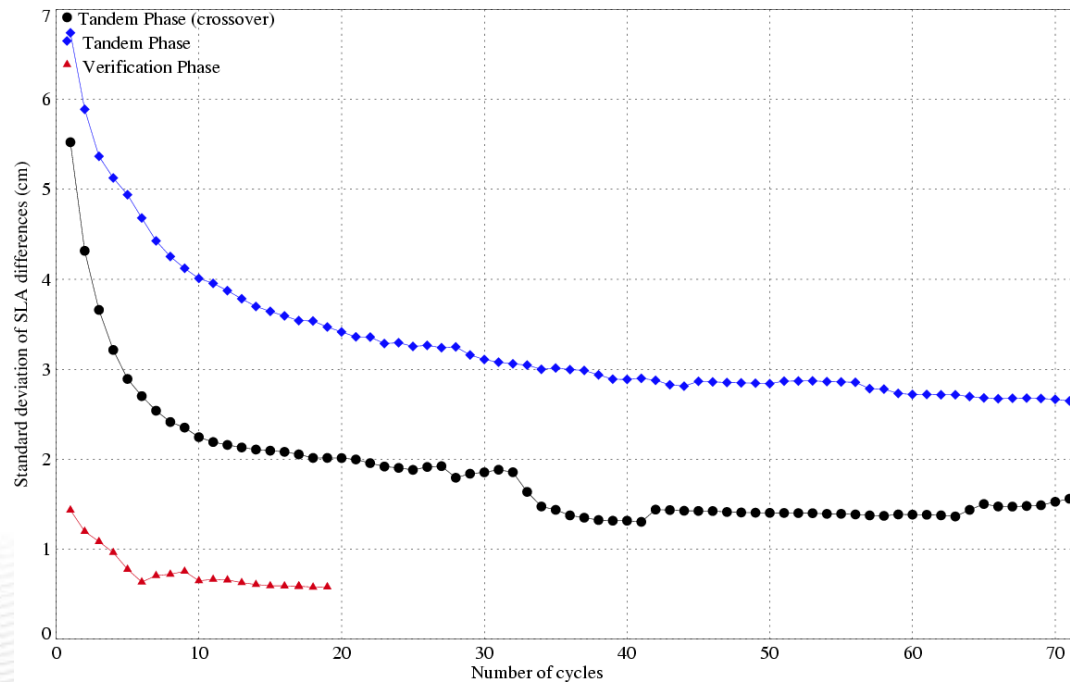


CalVal is a continuous activity

- CalVal activities will not stop just after the exact repeat phase
 - We must continue **to monitor and to improve** OSTM/J2 performances and data quality
 - Many (almost all) improvements in T/P / J1 consistency have been made after the repeat-track period
 - Data from the exact repeat phase will still be used to improve
 - We have other CalVal tools to do so, apart from exact repeat-track analysis (as shown previously on J1):
 - Direct comparisons, for detecting geographically correlated errors
 - Crossovers
 - Use of EnviSat
 - Other techniques, like comparisons to in-situ measurement will also help

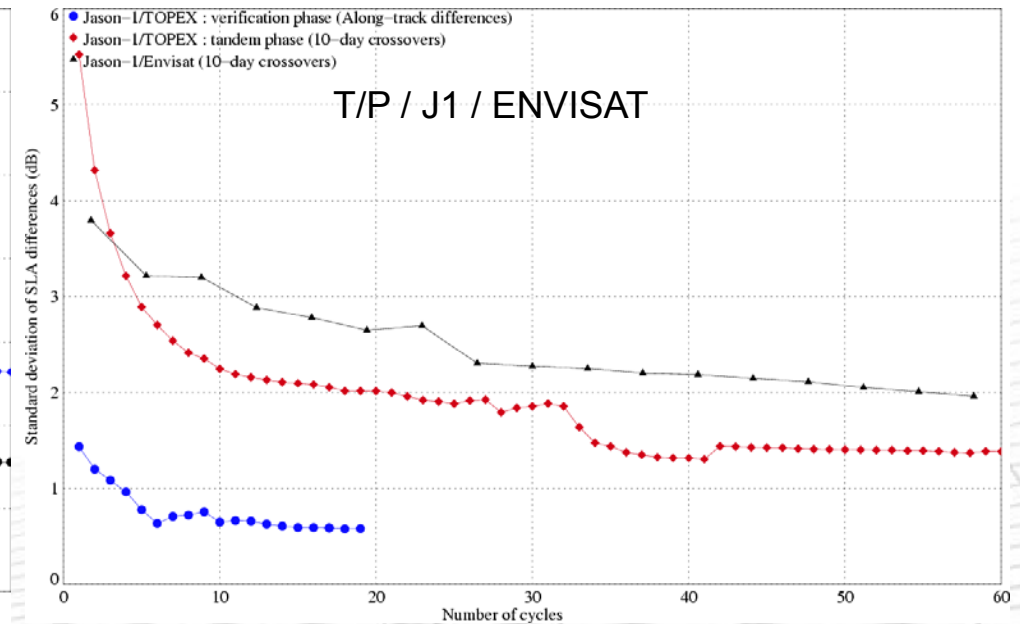
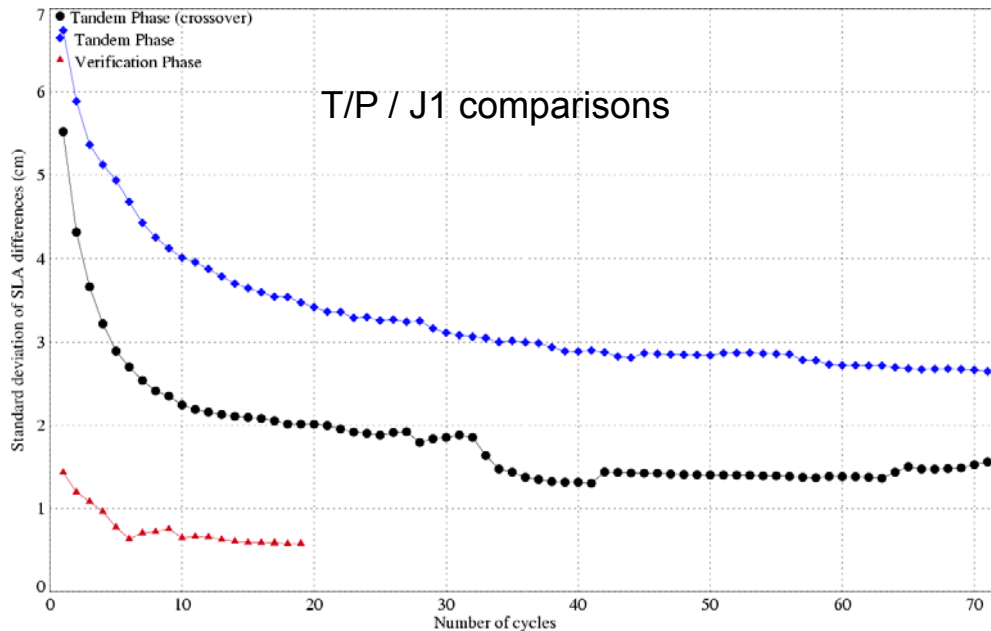
CalVal is a continuous activity

- Estimation of the (T/P – J1) consistency
 - During and after the exact repeat period
 - Using 3 different techniques



CalVal is a continuous activity

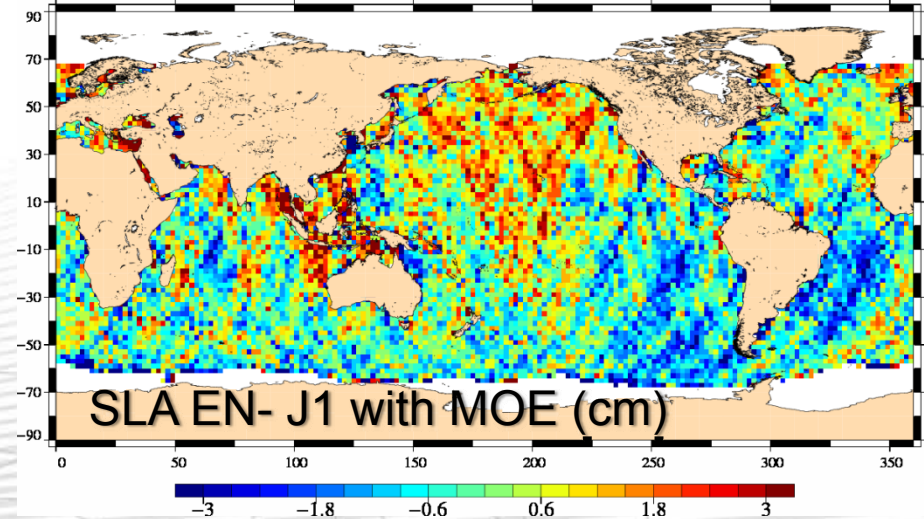
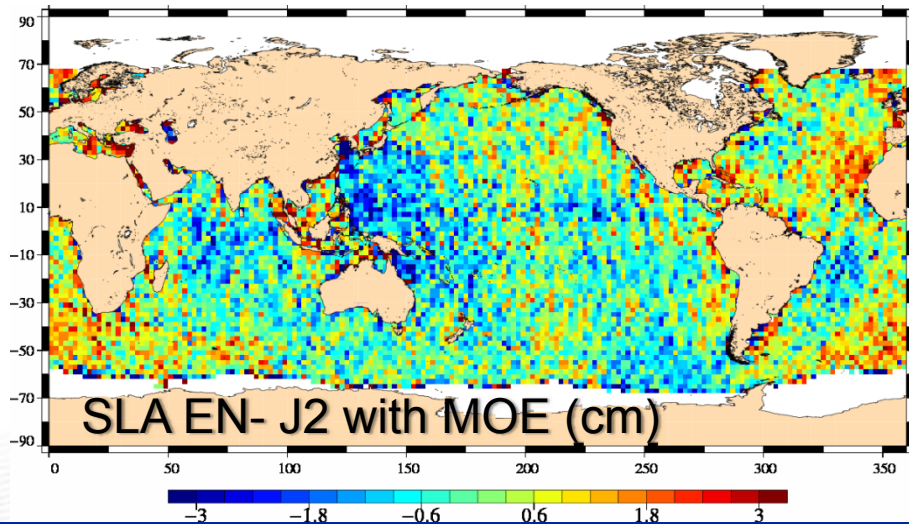
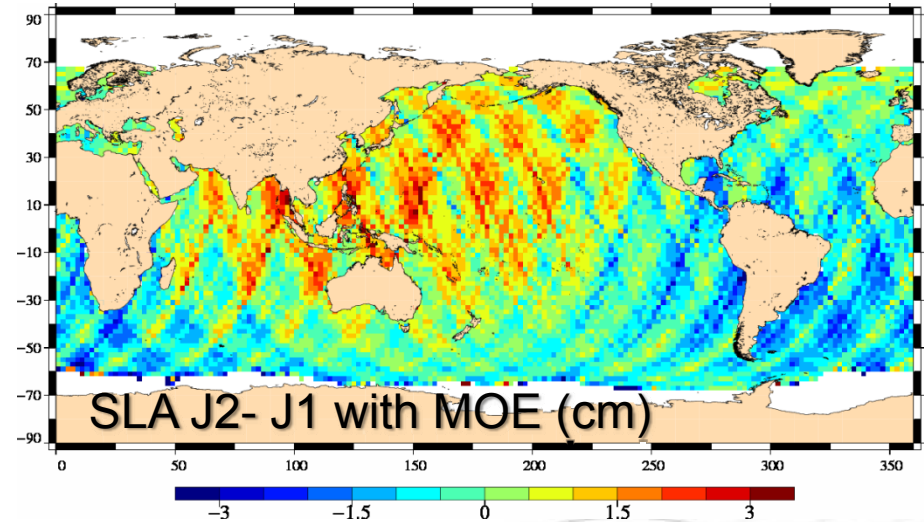
- Estimation of global consistency between different missions
 - During and after the exact repeat period
 - Using 3 different techniques



- Even less precise, other techniques are able to detect changes or to assess improvements

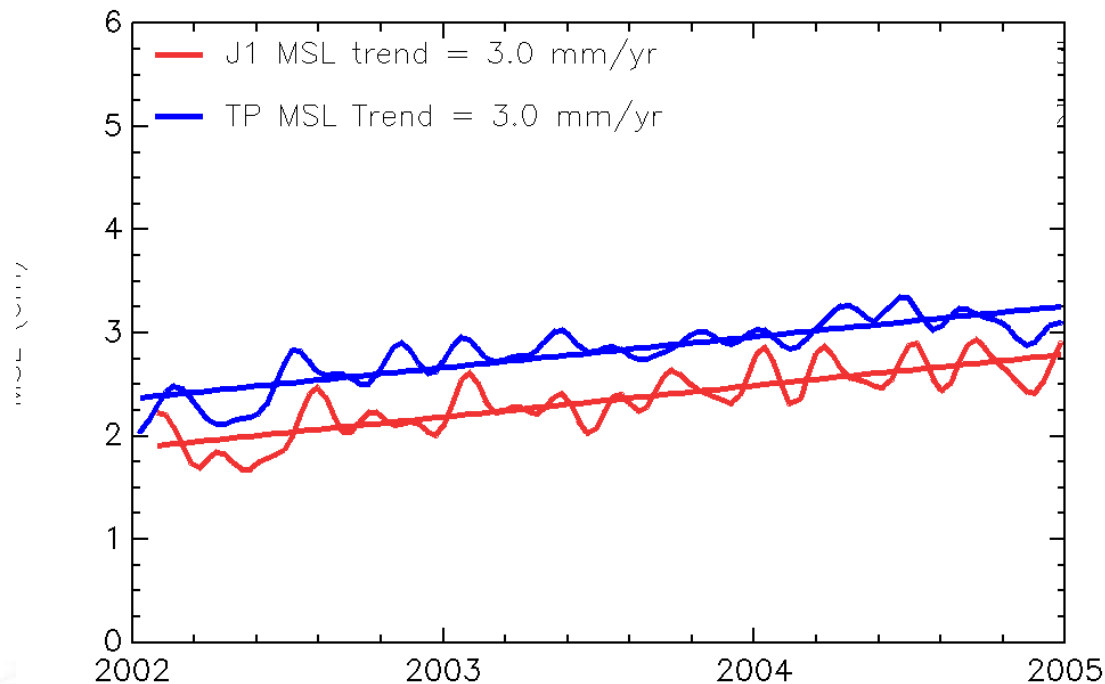
CalVal is a continuous activity

- Shown by M. Ablain in the POD splinter
- Cross-calibration with Envisat used to investigate differences between J1 and J2, even in the repeat-track period!
- Large structures observed in both EN/J1 and J2/J1 maps



CalVal is a continuous activity

- MSL estimations on different ground tracks, experience of T/P / J1



Conclusions

- CalVal results from analysis of 4 months of data:
 - Very good performances of the overall altimeter system and improvements relative to J1 (AMR/JMR, orbits)
 - No issue detected. Fully compliant to specified error budget
 - Very good SSH consistency between J1 and J2 (differences < 5 mm and constant)
 - Results as good as between T/P and J1 with 9 months of data and several years of studies
- Which issue/application requires further extension of the repeat-track configuration? And what is the accuracy requirement?
 - MSL is the more demanding application in terms of stability:
 - global and local estimates will be possible, as with T/P and J1
 - Seasonal signals not well observed?
 - Would require 2 years for annual signal
 - Will be observed anyway by other means (long time scales)
 - Possible scale error in iono corrections (J1 – J2) shown by S. Desai
 - More cycles would not help too much (observed on each cycle)
 -
 - Other features that have not been discovered so far?
 - Should be visible if they were present
 - Other events can occur (sensor failure...)
- CalVal activities will continue: other techniques, multi-mission
- It's time to feed other applications (than CalVal) for which the mission has been designed
- 4 to 6 months, depending on feasibility, **but we must take the decision today**