

Status of Jason-1/Jason-2 POE

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Jason-2: Comparison of different orbits to POE

Good agreement between different solutions, close or better than 1 cm for all orbits





Jason-2: Tracking data consistency

Orbits obtained with different tracking techniques can compare at 7 mm level in radial direction

- stable between reduced dynamic orbits (D/L GSFC Vs GPS JPL)
- affected by modeling errors on dynamic orbits (sharing the same models, Cnes D Vs Cnes G)





Jason-2: SLR residuals on different orbits

- Degraded RMS for non-GPS orbits when low elevation data is included
- Similar performance of SLR statistics for reduced dynamic orbits (JPL GPS, GSFC DL)
- SLR is included in GDR-POE solution
- CNES dynamic Doris and GPS orbits exhibit similar radial performance



RMS of common SLR residuals on core network(*)

(*) 7090YARR 7105WASH 7110MONU 7839GRAZ 7080FORT 7840HERS 8834WETZ 7810ZIMM



Jason-2: SLR residuals on different orbits

High elevation SLR residuals per cycle indicate a stable radial accuracy close to 1 cm for all orbits



RMS of SLR residuals on core network

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Jason-2: Doris and SAA

No conclusive sign of degradation due to SAA on Jason-2 doris residuals





Jason-2: Orbit comparison – Geographically correlated radial differences





Jason-2: Orbit comparison -Centering

- 120-days signature present in Z when comparing external orbits (JPL,GSFC) to CNES POE
- Long-term behavior (annual signal?) when all orbits are compared relative to Doris only orbits





Jason-2: External orbit comparison – Along/Cross track

 Cross-track mean reflects differences in SRP modeling
Along-track mean shows some beta angle dependent pattern with less evident correlation





Jason-2: Estimated empirical parameters

- Current model mean scale error is below 1 %
- Significant error around flip (higher when satellite is flying forward)







Jason-2: Orbit Performance - Crossovers

■ Jason-1 / Jason-2 indicate equivalent performance in term of crossover residuals



SSH differences at crossovers (Sel: |Lat|<50, bathy<-1000m, var ocean < 20 cm) SSH differences at crossovers (Sel: |Lat|<50, bathy<-1000m, var ocean < 20 cm)



Jason-1 performance - MOE

Corrected version of SAA model (new ground-track) is now implemented on both POE and MOE

 noticeable improvement on MOE overlaps and doris post-fit residuals (as no SAA correction was applied before April 05, 2009)









Jason-1 performance - POE

Comparison with external orbits indicate stable properties of the GDR orbits
Differences in surface forces attitude models





Jason-1 performance - POE

■ GSFC-CNES comparison:

Radial difference rate is stronger before Doris instrument change, indicating a N/S drift of about 2 mm/yr

Some geographically correlated pattern remain after cycle 091

Relative radial drift is small (<1 mm/yr) when the entire series is considered



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Conclusions

Jason-2 Doris, GPS, SLR POE complies with the accuracy required by GDR products

- Comparison of orbits from different groups
- High elevation SLR residuals
- Altimeter crossover residuals
- Some margin of improvement expected from next POD standards
 - SRP model and surface forces in general
 - Better modeling of time varying gravity
- Stable accuracy of Jason-1 POE after loss of GPS tracking and update of SAA model



Backups



















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JASON-2 SLR residuals on Doris and GPS orbits 7090 7105 7110 7839

7090 7105 7110 7839 7080 7840 8834 7810

Bias per station per cycle removed

Bias per station per cycle not removed



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Doris POE Time-Tagging

POE Doris time tagging accuracy better than 1.5 microsec, measured by

• GPS: Along track mean difference between GPS / Doris orbits (mean ~ 5 mm)



 SLR: Mean of along track SLR bias per pass over each cycle, from SLR residuals on Dorisonly orbits (mean ~ 8mm)





JASON-2 Doris residuals

JASON-2 POST FIT DORIS Residuals



