

An Introduction to the GPS-OGDR-SSHA Product for OSTM/Jason-2

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Abstract

We present a quantitative assessment of a new OSTM/Jason-2 value-added near-real-time (NRT) sea surface height product, the GPS-OGDR-SSH product. This research-grade product is identical to the formal OGDR-SSH product, except for two additional fields: a GPS-based orbit altitude, and a sea surface height anomaly derived by replacing the DORIS-DIODE orbit with the GPS-based orbit altitude. The GPS-OGDR-SSH product is typically available within 3.5-5 hours of real time and the GPS-based orbit altitude on the product has typical accuracies of < 1.0 cm (RMS). We describe the approach used to compute the NRT GPS-based orbit for OSTM/Jason-2 and present results that demonstrate the orbit accuracy. We also provide a comparison between the sea surface height component measurements provided on the OSTM/Jason-2 (GPS-)OGDRs and I/GDRs to assess their relative accuracy, particularly in light of the accuracy of the NRT GPS-based orbits. The GPSOGDR-SSH product is available via ftp at the Physical Oceanography Distributed Active Archive Center (PO.DAAC), http://podaac.jpl.nasa.gov/pub/sea_surface_height/ostm/preview/.

Motivation: OGDR-SSHA vs. IGDR SSHA

• GOAL: Improve accuracy of OSTM/Jason-2 NRT OGDR-SSHA by improving accuracy of NRT orbit for OSTM/Jason-2

SSHA Parameter		OGDR	IGDR	RMS Difference, IGDR-OGDR (mm)
Orbit Altitude		DIODE (DORIS)	MOE (DORIS)	38
Ku Range		Retracked	Retracked	22
Dry Troposphere		Predicted	Analyzed	2
Wet Troposphere:	AMR	Uncalibrated	Uncalibrated	< 1
	Model	Not Available	Available	
lonosphere:	ALT	Dual frequency	Dual frequency	13
	Model	Not Available	Available	
Sea State Bias		Uncalibrated	Uncalibrated	4
Inverse Barometer		Predicted	Analyzed	9
Pole Tide		Predicted	Predicted	0
HF Dealiasing		Not Available	Preliminary	
OGDR-SSHA				47

The GPS-OGDR-SSHA Product

Two GPS-based fields added to the OSTM/Jason-2 OGDR-

JPL's Ultra-Rapid GPS Orbit and Clock Product

 New product with orbit and clock solutions SSHA product: of GPS constellation. • Orbit altitude derived from near-real-time GPS-based precise • 3-D orbit accuracy of < 5 cm (RMS). orbit determination (POD) of OSTM/Jason-2. (gps_alt) • Latency of 1 hour. Radial orbit accuracy of < 1 cm (RMS). • Enables ambiguity resolved • Sea surface height anomaly derived from GPS-based orbit positioning and orbit determination. altitude. (gps_ssha) • Computed using GIPSY/OASIS software • Typical latency of 3.5-5 hours (or lag of 1 OGDR). with backward smoothing and ambiguity resolution. • Product released starting June 8, 2009. • Uses optimally distributed 40 out of 140 • Available at PO.DAAC: global terrestrial GPS sites. ftp://podaac.jpl.nasa.gov/pub/sea_surface_height/ostm/ Used for NRT GPS-based POD for OSTM/ preview/ Jason-2 since May 30, 2009.

GPS NRT Orbit Determination Approach



Orbit Differences with GPS-based POE: Repeat Cycle 34



• RMS of differences over complete cycle 34:

• DIODE: 40.9 mm, IGDR: 12.9 mm, NRT-GPS 4.8 mm

• Over entire cycle, NRT-GPS orbit has better agreement with GPS-based POE than IGDR orbit. • Some passes where IGDR orbit has better agreement with GPS-based POE.



- 24-hour POD arcs ending with each new telemetry dump.
- Ignore X-hours of tail of orbit solutions.
 - Tested X = 0, 1, and 2 hours.
- Append orbit solutions where not already defined.
- X = 1 hour adopted in GPS-**OGDR-SSHA**.

Orbit Differences with Next Day Precise GPS-based Orbit



Average of Daily Radial **RMS of Orbit Differences** w.r.t. Next-day Orbit. **GPS-based** Average Orbit (mm) NRT, X=0 6.8 3.9

3.1

1.7 **GPS POE**

- GPS-based next day and GPS-based POE agree to < 2 mm (RMS).
- 1-hour orbit cutoff requires latency of 1 OGDR lag, but provides significant (2.9 mm RMS) gain in radial orbit accuracy.
- 2-hour orbit cutoff provides additional 0.8 mm (RMS) improvement in

Geographically Correlated Orbit Differences: Repeat Cycle 34

OGDR orbit - GPS-based POE, (RMS, MIN, MAX) = (27, -118, 165) mm



GPSOGDR orbit - GPS-based POE, (RMS, MIN, MAX) = (3, -14, 19) mm



IGDR orbit - GPS-based POE, (RMS, MIN, MAX) = (9, -44, 44) mm



Sea Surface Height Cross-Over Variance Reduction w.r.t. IGDR orbit.



radial orbit accuracy, but requires lag of 2 OGDRs.

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• GPS-OGDR orbit provides order of magnitude reduction of geographically correlated errors compared to OGDR orbit.

• All GPS-based orbits provide smaller SSH cross-over residual variance than IGDR orbit. GPS-based next-day and POE orbits statistically identical. • Cross-over residual variance with GPS-based POE smaller than with GPS-OGDR orbit by 49 mm² • GPS-OGDR orbit has radial orbit accuracy of < 1 cm (RMS).