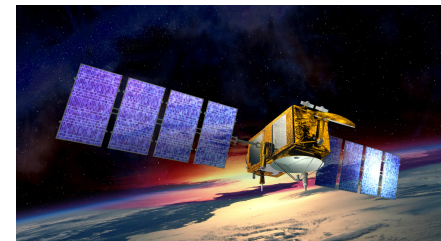
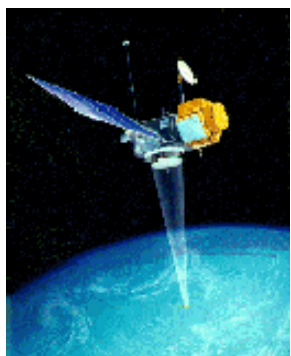


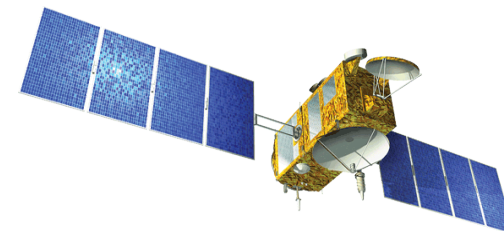
POD Splinter Summary

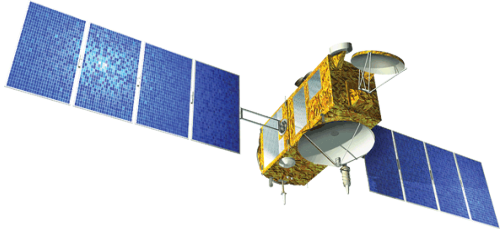


Luca Cerri (CNES)
Frank Lemoine (NASA GSFC)



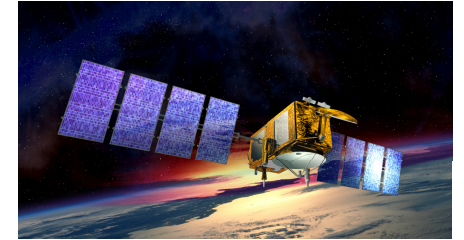
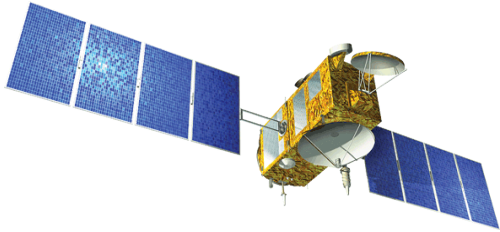
**OSTST 2011 POD Splinter
San Diego, California
October 19-21, 2011**





Session Summary (1)

- 8 oral talks; five posters.
- Updates by CNES, GSFC, JPL ESOC Analysis Centers (Status of POD on Jason-2; Assessment of Jason-2 Radial orbit quality; Reanalysis of Jason-1 and TOPEX; Status of GPS System performance).
- Discussion of proposed standards for GDR-D orbits (update to current GDR-C).
- Other detailed topics:
 1. Updated reference frame DORIS sites (DPOD2008) (**166 DORIS sites, vs. only 130 in ITRF2008**) (*Pascal Willis, IPGP/IGN*).
 2. Orbit Quality assessment through SSH Analyses (*Sabine Phillips, CLS*).
 3. Multi-mission Crossover analysis to investigate geographically correlated error, center-of-origin offsets, orientation of rotation axes (*Denise Dettmering, DGFI*)



Session Summary (2)

1. Improvements in ERS-1, ERS-2 Orbits; ITRF2005-series orbits available from: <ftp://dgn6.esoc.esa.int/reaper/>

(Poster by Michiel Otten et al.)

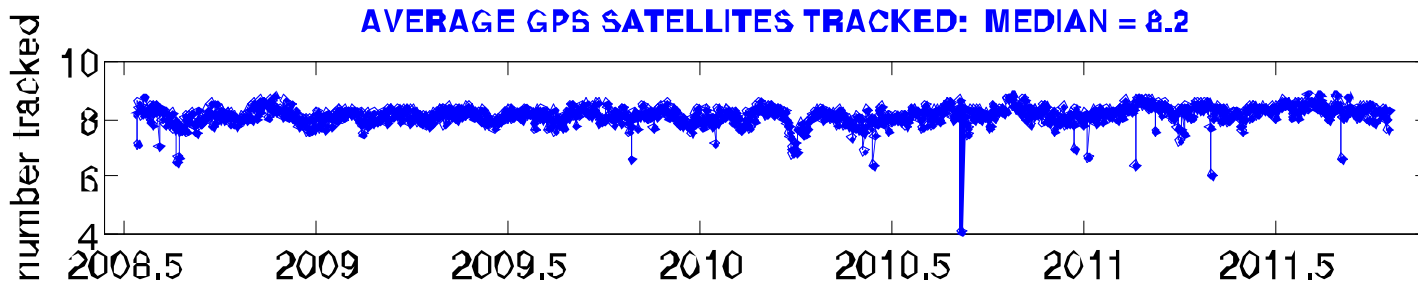
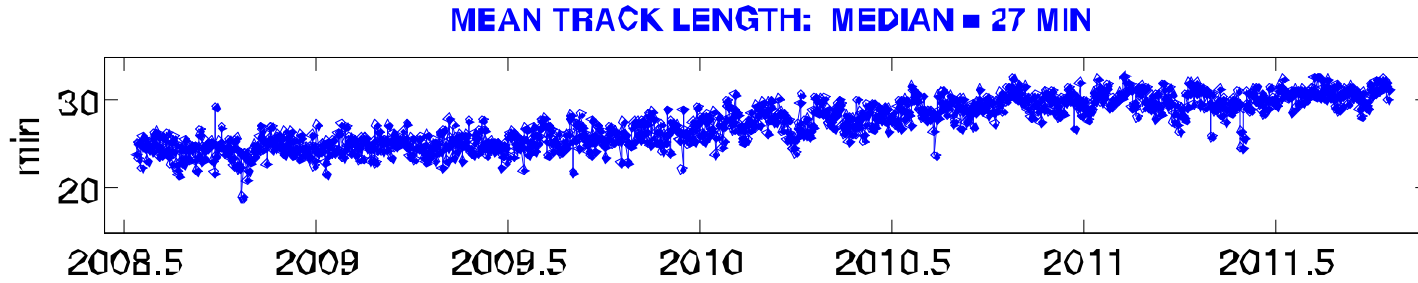
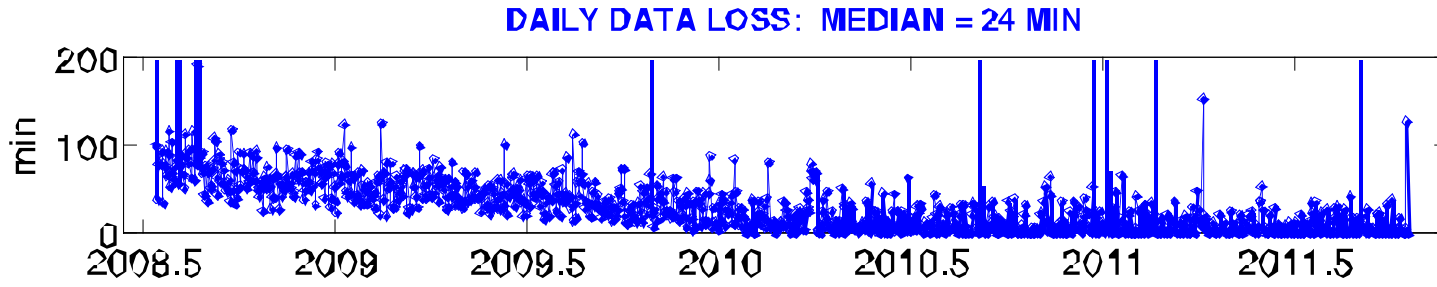
- Geographically correlated errors of **ERS** now in the same order of magnitude as TOPEX and Jason (2-3 mm RMS), thanks to new orbits *(Presentation by Denise Dettmering)*.

2. Improvements to DIODE Navigator (Real-time DORIS) for Jason-3, Sentinel-3 *(Poster by Christian Jayles)*.

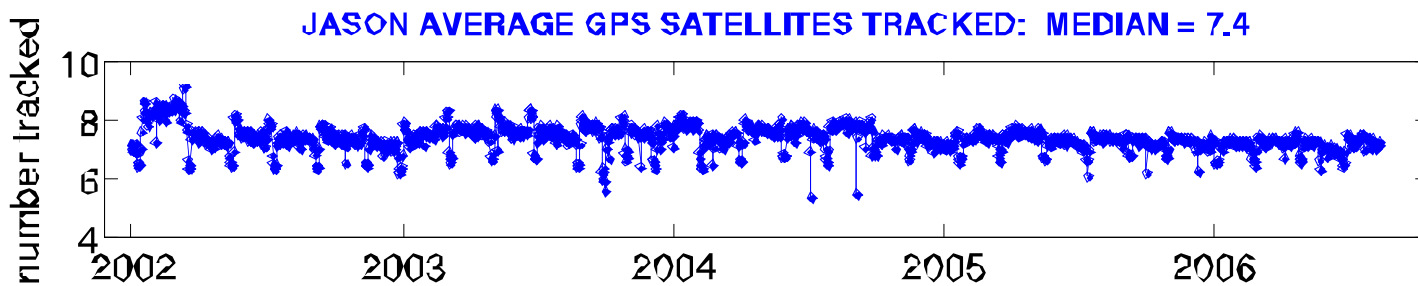


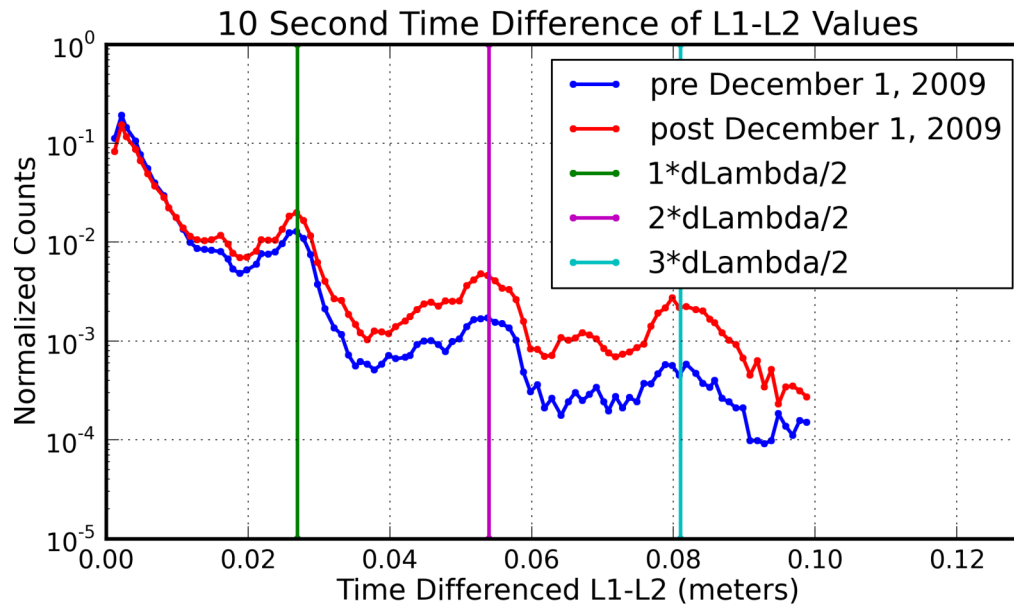
GPS Data Quality Over Time

JASON2/OSTM



JASON





$$d\lambda \equiv \lambda_{L2} - \lambda_{L1} = 24.44 \text{ cm} - 19.04 \text{ cm} = 5.40 \text{ cm}$$

**Solution: Phase Break if L1-L2
>1.5cm over 10 seconds**

Details: OSTMPODreport.pdf , email from Decarvalho June 14, 2011

Orbits comparison: radial component

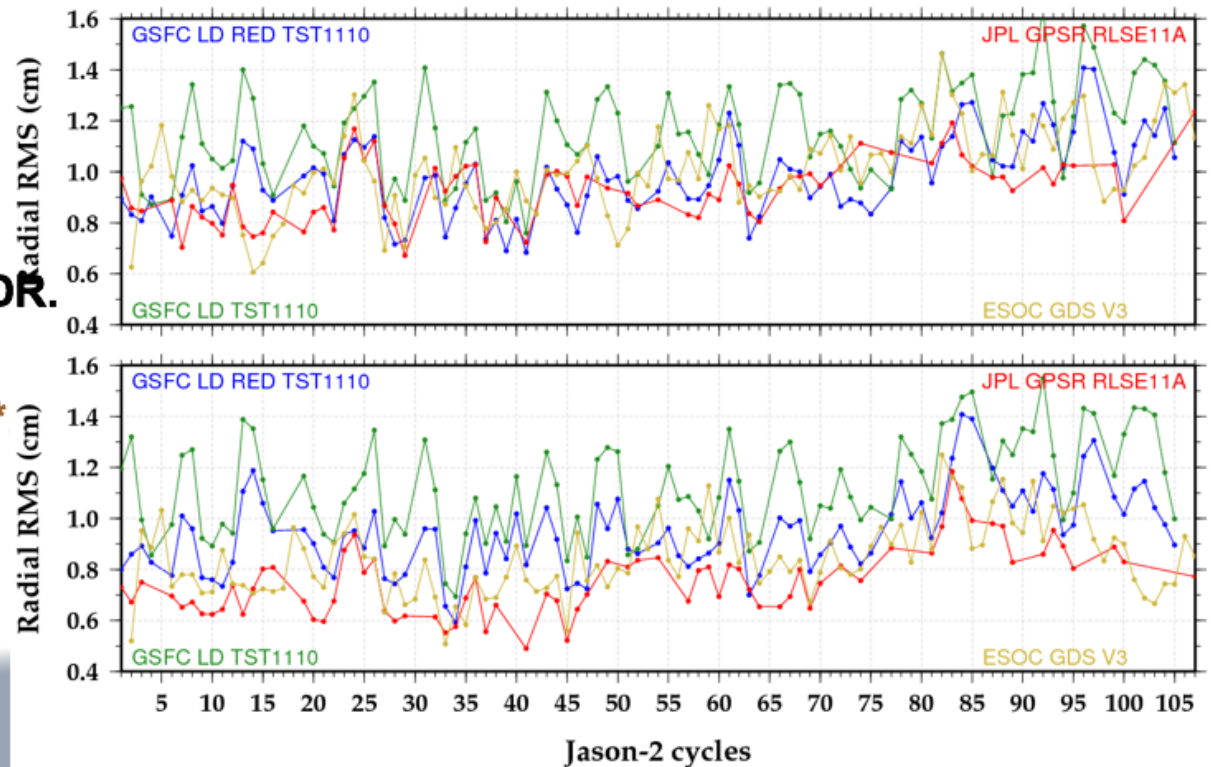
■ RMS of radial orbit differences relative to the GDR/GDR-D* solutions

GDR – others:

◆ Similar behavior in **GSFC** & **JPL** reduced dynamic solutions when compared to **GDR**.

GDR-D* – others:

- ◆ **JPL** close to **GDR-D***
- ◆ **60-day** signal btwn **GSFC** & **GDR/GDR-D*** dynamic orbits.
- ◆ **~1-cm** agreement.



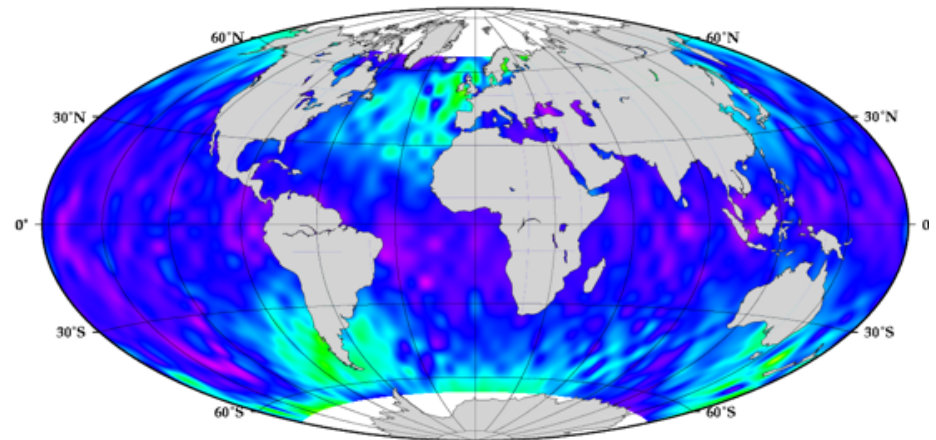
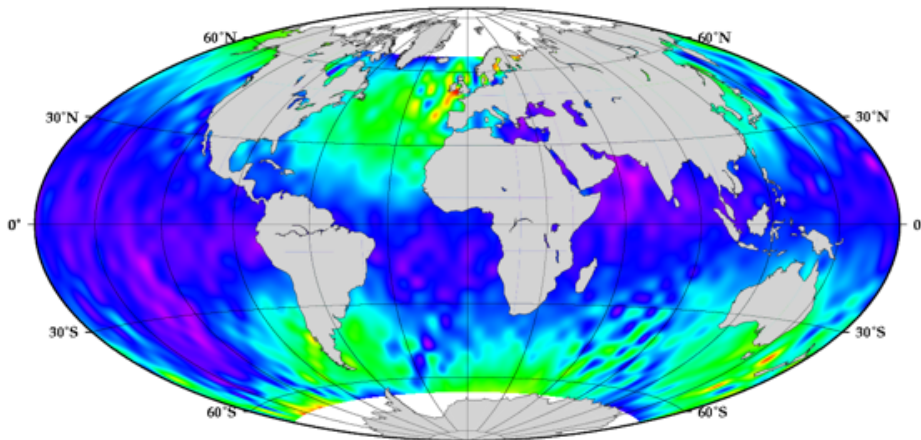
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120-day geographically correlated radial signal

■ Typical signature of SRP model differences **locally exceeding 1-cm**

Jason-2 GDR - GSFC LD TST1110 radial differences, cycles 1-105

Jason-2 GDR - GSFC LD RED TST1110 radial differences, cycles 1-105



120-day amplitude geographic projection



120-day amplitude geographic projection

◆ **GSFC reduced dynamic solution compensates for mismodeled SRP?**



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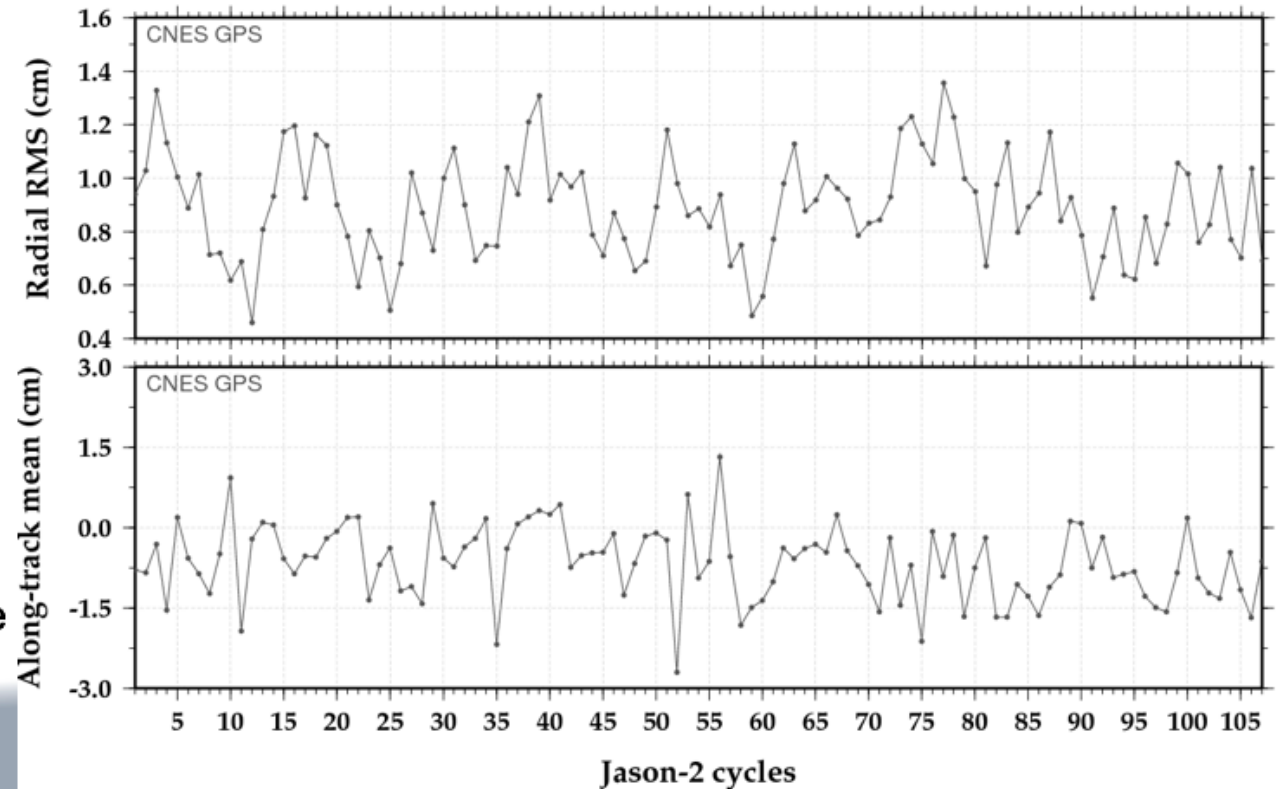
How is CNES GPS-based dynamic solution affected?

■ CNES GPS orbit differences relative to the CNES DORIS solution

◆ **No visible CNES GPS orbit degradation due to this effect.**

◆ **Likely reasons:**

- Solution more dynamically constrained.
- Rather conservative editing of the cycle slips.



Jason2: Mean geographically correlated radial differences GDRC-GDRD vs JPL/ESOS

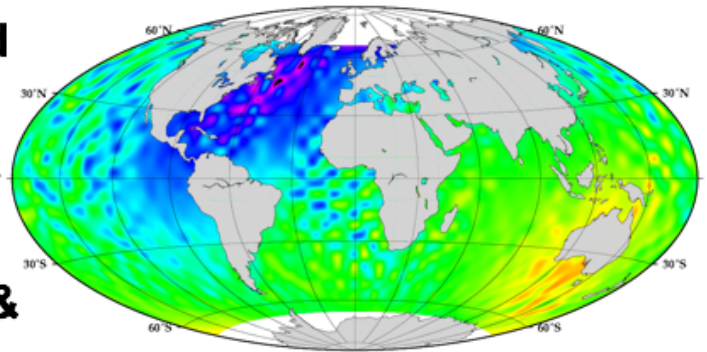
GDRC vs. JPL

GDRC vs. ESOC

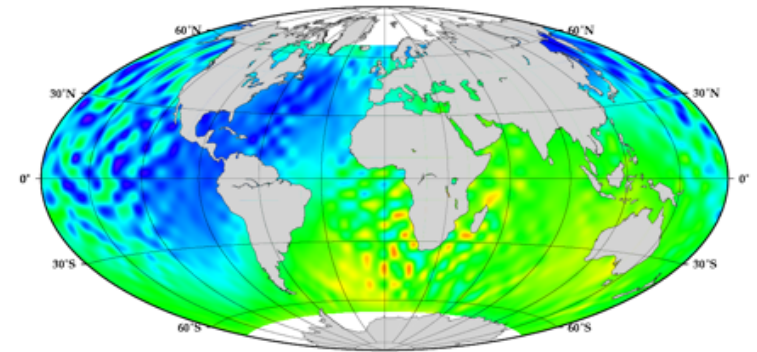
◆ Obvious gravity field modeling differences signatures btwn GDR & JPL/ESOC.

◆ GDR-D* completely clears the signatures.

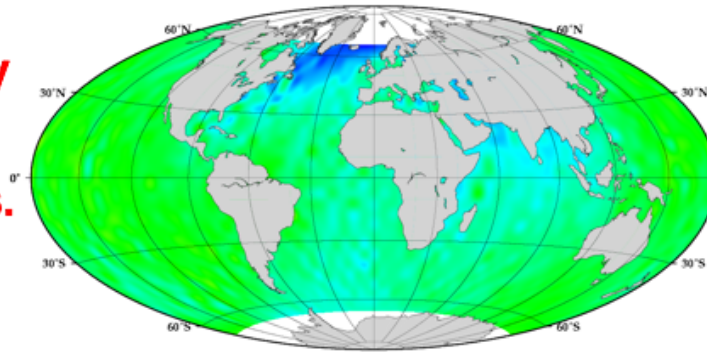
Jason-2 GDR - JPL GPSR RLSE11A radial differences, cycles 1-107



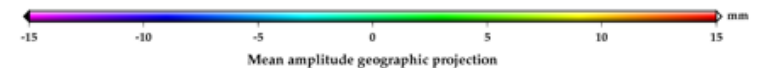
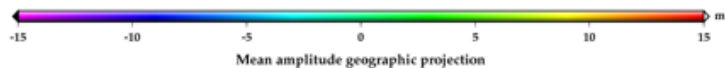
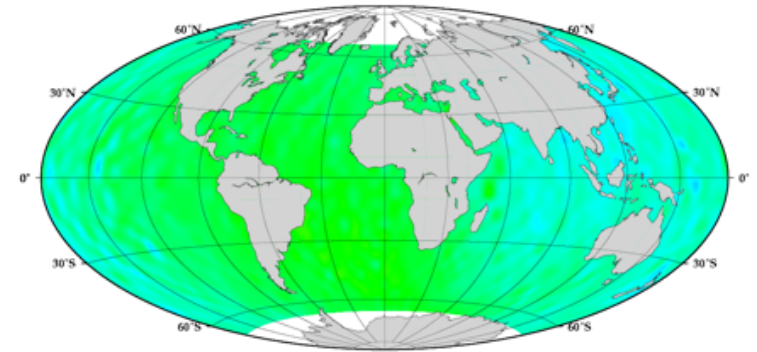
Jason-2 GDR - ESOC GDS V3 radial differences, cycles 1-107



Jason-2 GDRD* - JPL GPSR RLSE11A radial differences, cycles 1-107



Jason-2 GDRD* - ESOC GDS V3 radial differences, cycles 1-107



GDRD vs. JPL

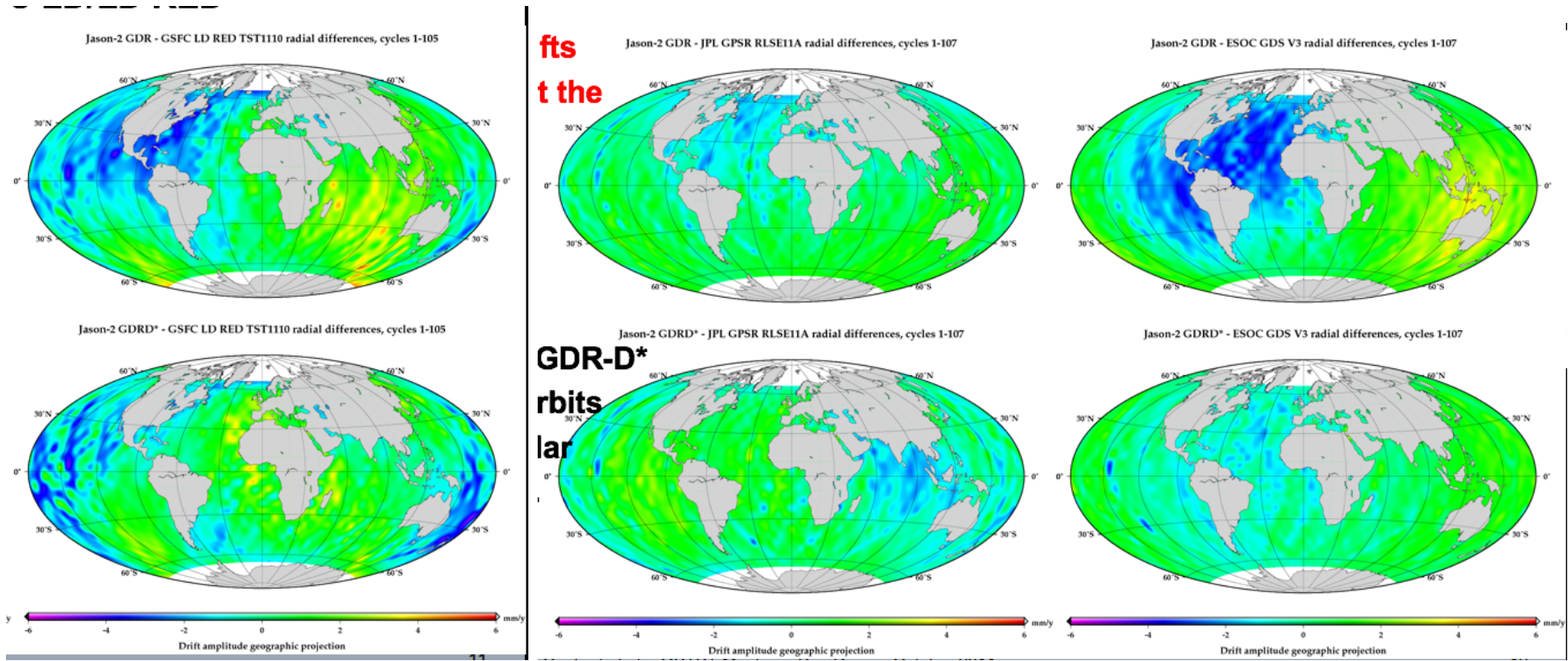
GDRD vs. ESOC

Jason-2 Geographic Radial Orbit Differences: Drift Between Orbit Series (mm/yr) (2008.5 - 2011.5)

GDRD vs GSFC

GDRD vs JPL/GPS

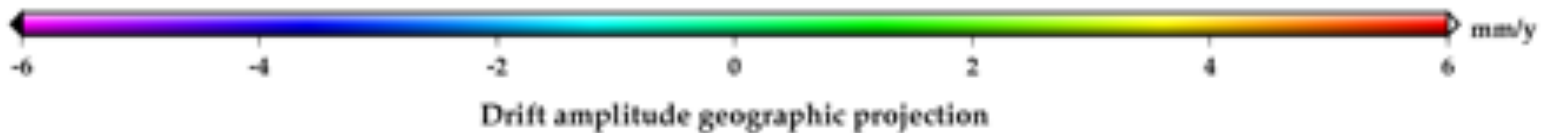
GDRD vs ESOC



GDRD vs GSFC

GDRD vs JPL/GPS

GDRD vs ESOC



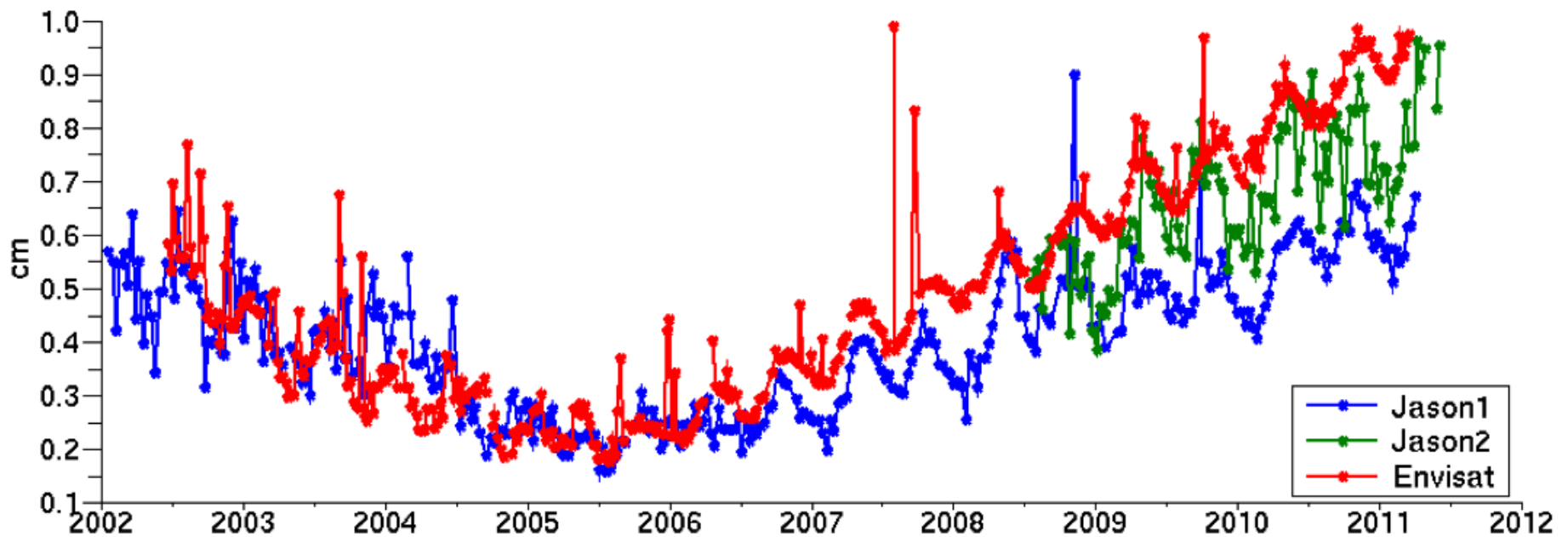
Gravity Field Modelling for Jason-1 & Jason-2 Orbits.

- GRACE-based solutions determined over as long a period as possible are the best candidates to use for Jason GDR production.
- Time-variable gravity (rates and to a lesser extent annual, semi-annual terms) will not *necessarily* be applicable at periods outside the GRACE mission - so a hybrid gravity solution is probably needed to span the full altimetry period (1993-2011).
- These GRACE-based secular and other terms do not capture all the variations in the gravity field that are observed.
- GDRC: EIGEN-GL04S static; annual + semiannual terms (*Determined 2003-2005*) (...+ ITRF2005)
- GDRD: EIGEN-GRGS-RL02bis_Mean_Field; rate, annual, semiannual to 50x50; (*Determined 2003-2010*) (....+ ITRF2008).

Radial orbit difference between GDR-C and GDR-D

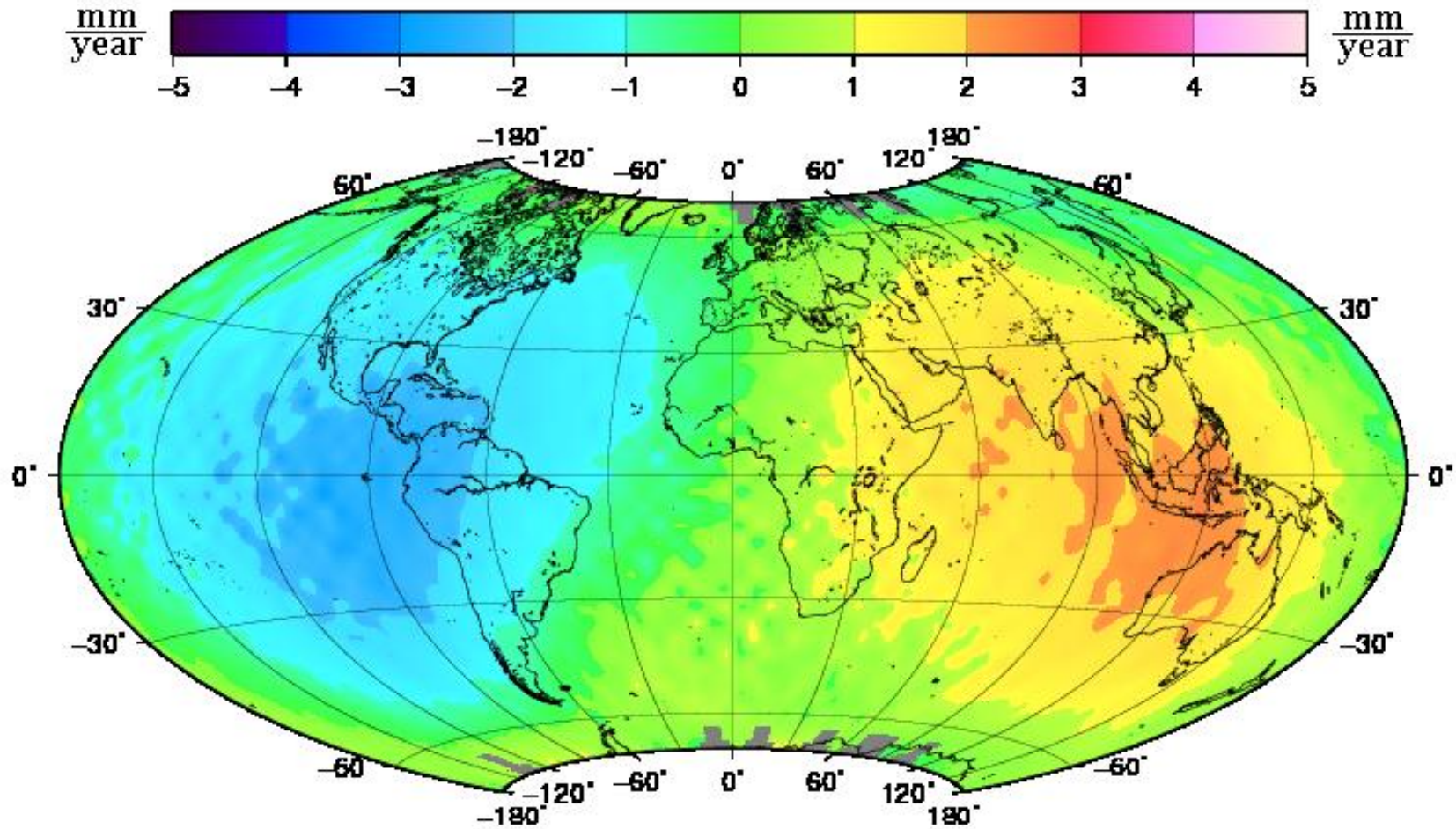
- RMS of radial differences is mostly driven by the new variable terms in the gravity field
- Below 1 cm RMS for Jason, reaches 1 cm on Envisat

RMS of Radial Difference between GDRC preliminary GDRD orbits





Jason2 std1007 (tvgsd-Eigen6s) Radial Orbit Rates, cycles 1-105 *(annual and semi-annual terms removed)*

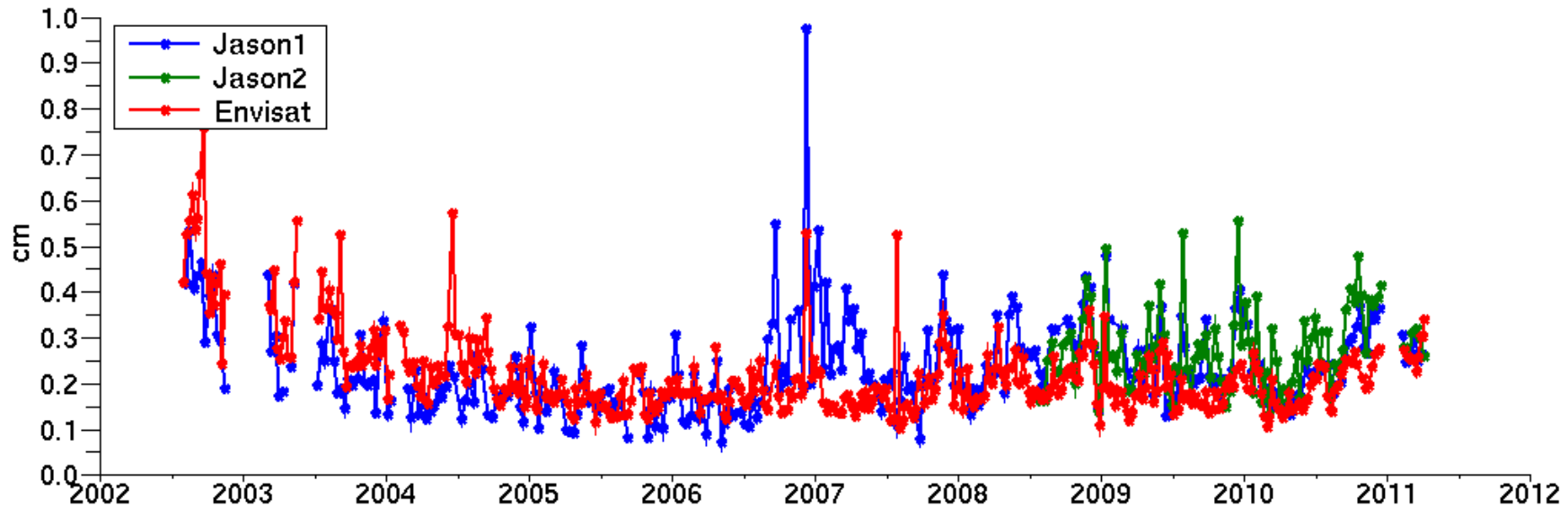


How does the mean model compare to the 10-day series

■ When the same series of 10-day gravity field test orbit is compared with the **GDRD** orbits, the comparison is quite stable through the 2002-2011 time span

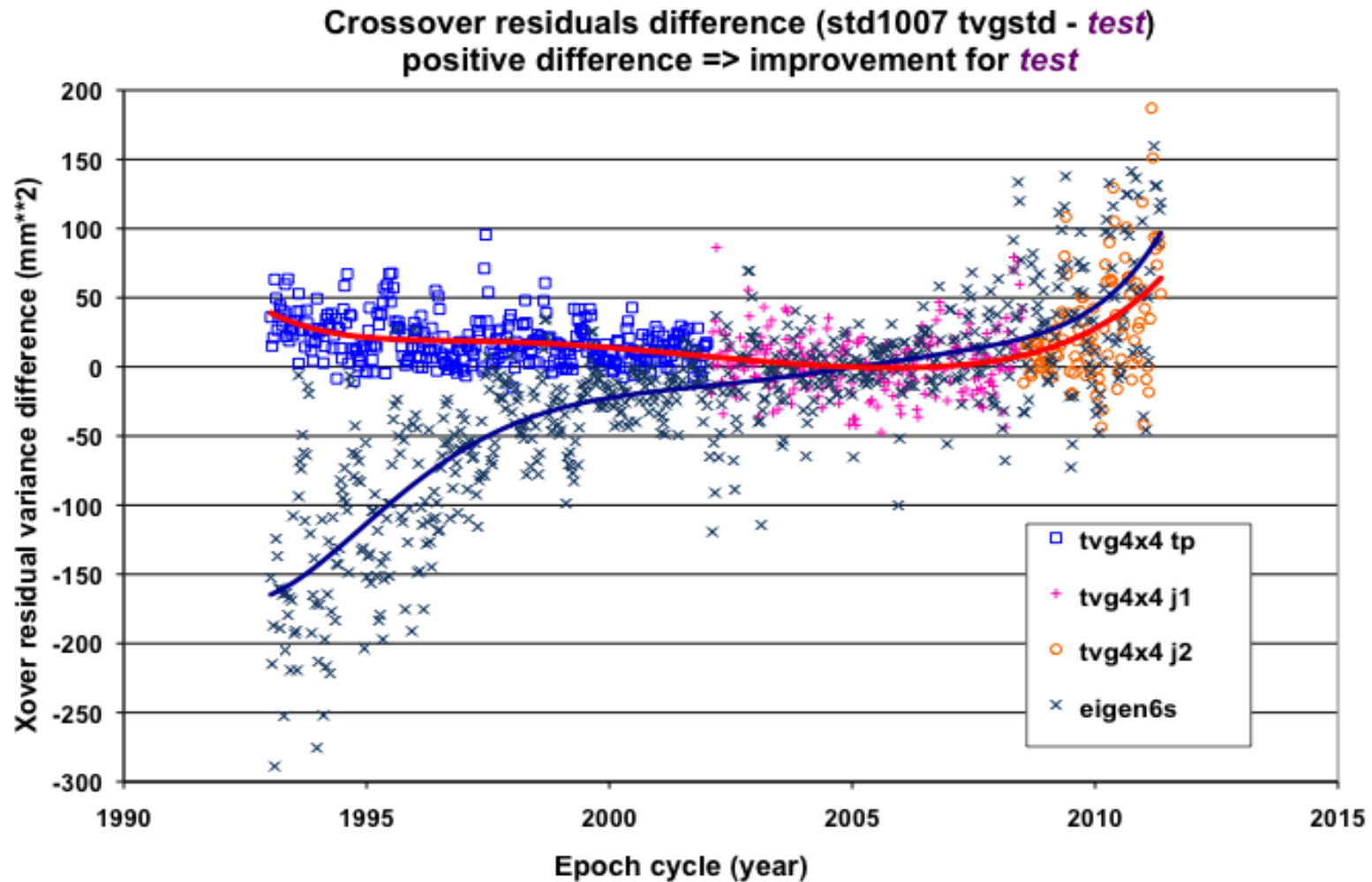
■ This indicates that **the new mean model captures most of the variability**

RMS of Radial Difference between GDRD orbits (using the new mean field) and GDRD orbits using the 10-day series





tvG4x4 Shows Orbit Improvement Across TP, J1, J2; Eigen6s only after about 2005



Conclusions

- Jason-2 radial orbit accuracy remains at 1 cm level; Agreement between centers & techniques at level of 6-9 mm.
- Gravity model (EIGEN-GL04S) is no longer adequate for Jason-2 POD in GDR-C. In GDR-D a new gravity model using more GRACE data will be used -- but we must monitor continued evolution & changes in the Earth's time-variable gravity field.
- Open issues:
 - (1) How to maintain consistency & stability in time (TP->J1->J2->J3) and across different missions?
 - (2) Radiation pressure mismodelling an open issue for Jason2 & other satellites.
 - (3) Modelling of geocenter (3-4 mm/yr in X-Y, 5 mm/yr Z) not included in present models -- no consensus model exists; Indications this signal is present in differences between POD centers.